

Convergence of 4th Runge-Kutta method on Least Square problem

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First draft : September 3, 2020

Last update : October 22, 2020

Setup

- ▶ Given $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{b} \in \mathbb{R}^m$, find $\mathbf{x} \in \mathbb{R}^n$ by solving

$$(\mathcal{P}) : \min_{\mathbf{x}} f(\mathbf{x}) = \frac{1}{2} \|\mathbf{Ax} - \mathbf{b}\|_2^2.$$

- ▶ We solve (\mathcal{P}) by the 4th-order Runge Kutta method:

$$\mathbf{x}_{k+1} = \mathbf{x}_k + \frac{h}{6} (\mathbf{s}_1 + 2\mathbf{s}_2 + 2\mathbf{s}_3 + \mathbf{s}_4)$$

where

$$\begin{aligned} \mathbf{s}_1 &= \nabla f(\mathbf{x}_k) \\ \mathbf{s}_2 &= \nabla f\left(\mathbf{x}_k + \frac{h}{2}\mathbf{s}_1\right) \\ \mathbf{s}_3 &= \nabla f\left(\mathbf{x}_k + \frac{h}{2}\mathbf{s}_2\right) \\ \mathbf{s}_4 &= \nabla f(\mathbf{x}_k). \end{aligned}$$

The RK4 update on least square

- ▶ After lots of algebra, the RK4 update on least square problem (\mathcal{P}) is

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \left(h\mathbf{I} - \frac{h^2}{2}\mathbf{Q} + \frac{h^3}{6}\mathbf{Q}^2 - \frac{h^4}{24}\mathbf{Q}^3 \right) (\mathbf{Q}\mathbf{x}_k - \mathbf{p}),$$

where $\mathbf{Q} = \mathbf{A}^\top \mathbf{A}$, $\mathbf{p} = \mathbf{A}^\top \mathbf{b}$.

- ▶ The update can also be expressed as

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \mathbf{H}\nabla f(\mathbf{x}_k),$$

with

$$\mathbf{H} = h\mathbf{I} - \frac{h^2}{2}\mathbf{Q} + \frac{h^3}{6}\mathbf{Q}^2 - \frac{h^4}{24}\mathbf{Q}^3.$$

- ▶ This document: discuss the convergence of this update.

Convergence of RK4 update

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \left(h\mathbf{I} - \frac{h^2}{2}\mathbf{Q} + \frac{h^3}{6}\mathbf{Q}^2 - \frac{h^4}{24}\mathbf{Q}^3 \right) (\mathbf{Q}\mathbf{x}_k - \mathbf{p}).$$

- ▶ Let \mathbf{x}^* be the minimizer. The 1st-order optimality condition $\nabla f(\mathbf{x}^*) = 0$ gives $\mathbf{p} = \mathbf{Q}\mathbf{x}^*$, so

$$\begin{aligned} \mathbf{x}_{k+1} - \mathbf{x}^* &= \mathbf{x}_k - \left(h\mathbf{I} - \frac{h^2}{2}\mathbf{Q} + \frac{h^3}{6}\mathbf{Q}^2 - \frac{h^4}{24}\mathbf{Q}^3 \right) (\mathbf{Q}\mathbf{x}_k - \mathbf{p}) - \mathbf{x}^* \\ &= \mathbf{x}_k - \mathbf{x}^* - \left(h\mathbf{I} - \frac{h^2}{2}\mathbf{Q} + \frac{h^3}{6}\mathbf{Q}^2 - \frac{h^4}{24}\mathbf{Q}^3 \right) \mathbf{Q}(\mathbf{x}_k - \mathbf{x}^*) \\ &= \left(\mathbf{I} - h\mathbf{Q} + \frac{h^2}{2}\mathbf{Q}^2 - \frac{h^3}{6}\mathbf{Q}^3 + \frac{h^4}{24}\mathbf{Q}^4 \right) (\mathbf{x}_k - \mathbf{x}^*) \\ \|\mathbf{x}_{k+1} - \mathbf{x}_k\|_2 &= \left\| \left(\mathbf{I} - h\mathbf{Q} + \frac{h^2}{2}\mathbf{Q}^2 - \frac{h^3}{6}\mathbf{Q}^3 + \frac{h^4}{24}\mathbf{Q}^4 \right) (\mathbf{x}_k - \mathbf{x}^*) \right\|_2 \\ &\stackrel{(*)}{\leq} \left\| \mathbf{I} - h\mathbf{Q} + \frac{h^2}{2}\mathbf{Q}^2 - \frac{h^3}{6}\mathbf{Q}^3 + \frac{h^4}{24}\mathbf{Q}^4 \right\|_2 \|\mathbf{x}_k - \mathbf{x}^*\|_2 \end{aligned}$$

(*) : $\|\mathbf{M}\mathbf{x}\|_2 \leq \|\mathbf{M}\|_2 \|\mathbf{x}\|_2$

- ▶ The update converges if

$$\left\| \mathbf{I} - h\mathbf{Q} + \frac{h^2}{2}\mathbf{Q}^2 - \frac{h^3}{6}\mathbf{Q}^3 + \frac{h^4}{24}\mathbf{Q}^4 \right\|_2 < 1.$$

Convergence of RK4 update

- ▶ Let $\mathbf{V}\Sigma\mathbf{V}^\top$ be the eigendecomposition of \mathbf{Q} . As norm is invariant to orthogonal transform, we have

$$\left\| \mathbf{I} - h\Sigma + \frac{h^2}{2}\Sigma^2 - \frac{h^3}{6}\Sigma^3 + \frac{h^4}{24}\Sigma^4 \right\|_2 < 1. \quad (1)$$

- ▶ The matrix in (1) is diagonal, so (1) is true if the largest absolute value of the diagonal matrix is smaller than 1. This translates as follows. Let $\phi_i(h, \lambda_i) = 1 - h\lambda_i + \frac{h^2}{2}\lambda_i^2 - \frac{h^3}{6}\lambda_i^3 + \frac{h^4}{24}\lambda_i^4$,

$$\text{RK4 update converges} \iff \max_i |\phi_i(h, \lambda_i)| < 1.$$

Furthermore, we can pick h by minimizing this value as

$$h = \min_h \max_i |\phi_i(h, \lambda_i)|.$$

- ▶ In general, h can be complex-valued. For $\mathbf{Q} = \mathbf{A}^\top \mathbf{A}$ that is positive definite (i.e., \mathbf{A} is full rank), h reduces to real value because eigenvalues of $\mathbf{A}^\top \mathbf{A}$ are real.

Convergence rate of RK4 update

- ▶ To derive (asymptotic) convergence rate of the RK4 method, we go back to the form

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \mathbf{H}\nabla f(\mathbf{x}_k). \quad (2)$$

By looking at (2), we have to consider variable metric: the weighted norm with respect to a symmetric positive definite matrix \mathbf{U} defined as

$$\|\mathbf{x}\|_{\mathbf{U}} = \langle \mathbf{x}, \mathbf{U}\mathbf{x} \rangle^{\frac{1}{2}}.$$

- ▶ We now derive the convergence rate: first, assume $\mathbf{H}(h)$ is non-singular (so \mathbf{H}^{-1} exists), from (2) we have

$$\begin{aligned} \|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 &\stackrel{(2)}{=} \|\mathbf{x}_k - \mathbf{H}\nabla f(\mathbf{x}_k) - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 \\ &= \|(\mathbf{x}_k - \mathbf{x}^*) - \mathbf{H}\nabla f(\mathbf{x}_k)\|_{\mathbf{H}^{-1}}^2. \end{aligned}$$

Simplifying notation: let $\mathbf{g}_k = \nabla f(\mathbf{x}_k)$, then

$$\|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 = \|(\mathbf{x}_k - \mathbf{x}^*) - \mathbf{H}\mathbf{g}_k\|_{\mathbf{H}^{-1}}^2.$$

$$\begin{aligned}
\|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 &= \|(\mathbf{x}_k - \mathbf{x}^*) - \mathbf{H}\mathbf{g}_k\|_{\mathbf{H}^{-1}}^2 \\
&= \left\langle (\mathbf{x}_k - \mathbf{x}^*) - \mathbf{H}\mathbf{g}_k, \mathbf{H}^{-1} \left((\mathbf{x}_k - \mathbf{x}^*) - \mathbf{H}\mathbf{g}_k \right) \right\rangle \\
&= \left\langle (\mathbf{x}_k - \mathbf{x}^*) - \mathbf{H}\mathbf{g}_k, \mathbf{H}^{-1}(\mathbf{x}_k - \mathbf{x}^*) - \mathbf{g}_k \right\rangle \\
&= \|\mathbf{x}_k - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 + \|\mathbf{g}_k\|_{\mathbf{H}}^2 - 2\langle \mathbf{g}_k, \mathbf{x}_k - \mathbf{x}^* \rangle.
\end{aligned}$$

As f is convex, its first-order Taylor approximation is a global under estimator: for any $\mathbf{y}, \mathbf{x} \in \text{dom} f$, then $f(\mathbf{y}) \geq f(\mathbf{x}) + \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle$. Put $\mathbf{y} = \mathbf{x}^*$ and $\mathbf{x} = \mathbf{x}_k$ gives $f(\mathbf{x}^*) \geq f(\mathbf{x}_k) + \langle \mathbf{g}_k, \mathbf{x}^* - \mathbf{x}_k \rangle$, rearrange gives

$$-\langle \mathbf{g}_k, \mathbf{x}_k - \mathbf{x}^* \rangle \leq -(f(\mathbf{x}_k) - f(\mathbf{x}^*)).$$

So $\|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 \leq \|\mathbf{x}_k - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 + \|\mathbf{g}_k\|_{\mathbf{H}}^2 - 2(f(\mathbf{x}_k) - f(\mathbf{x}^*))$.

Rearrange again gives

$$f(\mathbf{x}_k) - f(\mathbf{x}^*) \leq \frac{1}{2} \|\mathbf{x}_k - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 - \frac{1}{2} \|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 + \frac{1}{2} \|\mathbf{g}_k\|_{\mathbf{H}}^2.$$

Simplify notation, let $f^* = f(\mathbf{x}^*)$ and $f_k = f(\mathbf{x}_k)$

$$f_k - f^* \leq \frac{1}{2} \|\mathbf{x}_k - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 - \frac{1}{2} \|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 + \frac{1}{2} \|\mathbf{g}_k\|_{\mathbf{H}}^2.$$

Convergence rate of RK4 update

Take iteration counter from k to 0:

$$\begin{aligned}f_k - f^* &\leq \frac{1}{2} \|\mathbf{x}_k - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 - \frac{1}{2} \|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 + \frac{1}{2} \|\mathbf{g}_k\|_{\mathbf{H}}^2 \\f_{k-1} - f^* &\leq \frac{1}{2} \|\mathbf{x}_{k-1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 - \frac{1}{2} \|\mathbf{x}_k - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 + \frac{1}{2} \|\mathbf{g}_{k-1}\|_{\mathbf{H}}^2 \\f_{k-2} - f^* &\leq \frac{1}{2} \|\mathbf{x}_{k-2} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 - \frac{1}{2} \|\mathbf{x}_{k-1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 + \frac{1}{2} \|\mathbf{g}_{k-2}\|_{\mathbf{H}}^2 \\&\vdots \\f_0 - f^* &\leq \frac{1}{2} \|\mathbf{x}_0 - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 - \frac{1}{2} \|\mathbf{x}_1 - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 + \frac{1}{2} \|\mathbf{g}_0\|_{\mathbf{H}}^2\end{aligned}$$

Sum all the inequalities

$$\begin{aligned}\sum_{i=0}^k (f_i - f^*) &\leq \frac{\|\mathbf{x}_0 - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2}{2} - \frac{\|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2}{2} + \frac{1}{2} \sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2 \\&\leq \frac{\|\mathbf{x}_0 - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2}{2} + \frac{1}{2} \sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2.\end{aligned}$$

Convergence rate of RK4 update

We have

$$\sum_{i=0}^k (f_i - f^*) \leq \frac{\|\mathbf{x}_0 - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2}{2} + \frac{1}{2} \sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2.$$

Since

$$(k+1)(f_i^{\text{best}} - f^*) \leq \sum_{i=0}^k (f_i - f^*)$$

we arrive

$$f_i^{\text{best}} - f^* \leq \frac{\|\mathbf{x}_0 - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2}{2(k+1)} + \frac{1}{2(k+1)} \sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2.$$

If $\sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2$ grows slower than k , the term $\sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2 \rightarrow 0$ we have convergence rate $\frac{1}{k}$.

Convergence of Projected RK4 update

- ▶ We now consider a general problem: let $\mathcal{C} \subset \mathbb{R}^n$ be a convex set

$$(\mathcal{P}_{\mathcal{C}}) : \min_{\mathbf{x} \in \mathcal{C}} f(\mathbf{x}) = \frac{1}{2} \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2^2.$$

- ▶ We solve it by the projected RK4 (pRK4):

$$\mathbf{x}_{k+1} = P_{\mathcal{C}}\left(\mathbf{x}_k - \mathbf{H}\nabla f(\mathbf{x}_k)\right), \quad (3)$$

where $P_{\mathcal{C}}$ is the projection.

- ▶ The previous convergence analysis still holds for pRK4. The proof starts with the non-expansive property of projection

$$\begin{aligned} \|\mathbf{x}_{k+1} - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2 &\stackrel{(3)}{=} \|P_{\mathcal{C}}\left(\mathbf{x}_k - \mathbf{H}\nabla f(\mathbf{x}_k)\right) - P_{\mathcal{C}}(\mathbf{x}^*)\|_{\mathbf{H}^{-1}}^2 \\ &\leq \|\mathbf{x}_k - \mathbf{H}\nabla f(\mathbf{x}_k) - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2, \end{aligned}$$

and then proceed.

Last page - summary

- ▶ Given $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{b} \in \mathbb{R}^m$, find $\mathbf{x} \in \mathbb{R}^n$ by solving

$$(\mathcal{P}) : \min_{\mathbf{x}} f(\mathbf{x}) = \frac{1}{2} \|\mathbf{Ax} - \mathbf{b}\|_2^2.$$

- ▶ We solve (\mathcal{P}) by the 4th-order Runge Kutta method:

$$\mathbf{x}_{k+1} = \mathbf{x}_k + \frac{h}{6} (\mathbf{s}_1 + 2\mathbf{s}_2 + 2\mathbf{s}_3 + \mathbf{s}_4)$$

$$\begin{aligned} \mathbf{s}_1 &= \nabla f(\mathbf{x}_k) & \mathbf{s}_2 &= \nabla f(\mathbf{x}_k + \frac{h}{2}\mathbf{s}_1) \\ \mathbf{s}_3 &= \nabla f(\mathbf{x}_k + \frac{h}{2}\mathbf{s}_2) & \mathbf{s}_4 &= \nabla f(\mathbf{x}_k). \end{aligned}$$

- ▶ Convergence

$$f_i^{\text{best}} - f^* \leq \frac{\|\mathbf{x}_0 - \mathbf{x}^*\|_{\mathbf{H}^{-1}}^2}{2(k+1)} + \frac{1}{2(k+1)} \sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2.$$

If $\sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2$ grows slower than k , the term $\sum_{i=0}^k \|\mathbf{g}_i\|_{\mathbf{H}}^2 \rightarrow 0$ we have convergence rate $\frac{1}{k}$.

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