

# Convergence of PALM on non-convex problems

Part 1 : generated sequence is non-increasing with finite length trajectory

Andersen Ang

Mathématique et recherche opérationnelle  
UMONS  
Belgium

Email: [manshun.ang@umons.ac.be](mailto:manshun.ang@umons.ac.be)

Homepage: [angms.science](http://angms.science)

August 17, 2018

Proximal alternating linearized minimization or nonconvex and nonsmooth problems

J Bolte, S Sabach, M Teboulle

Mathematical Programming 146 (1-2), 459-494, 2014

# The problem

## Class of function

$$\min_{x \in \mathbb{R}^n, y \in \mathbb{R}^m} \Phi(x, y) = f(x) + g(y) + H(x, y),$$

- Optimization variables :  $x, y$
- Constraint sets  $\mathcal{X} \subset \mathbb{R}^n, \mathcal{Y} \subset \mathbb{R}^m$  moved into  $f, g$  by using indicator functions  $\mathcal{I}_{\mathcal{X}}, \mathcal{I}_{\mathcal{Y}}$
- $f, g$  are extended value functions : e.g.  $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup +\infty$
- $H$  is smooth (it is partially Lipschitz)
- No convexity will be assumed on  $f, g, H$

Problem : minimize  $\Phi(x, y) = f(x) + g(y) + H(x, y)$ .

Starts with  $(x^0, y^0) \in \text{dom}\Phi$ , PALM generate  $(x^k, y^k)$  as

$$\begin{aligned}x_k &\in \text{prox}_{f, c_k} \left( x^k - \frac{1}{c_k} \nabla_x H(x^k, y^k) \right), \\y_k &\in \text{prox}_{g, d_k} \left( y^k - \frac{1}{d_k} \nabla_x H(x^{k+1}, y^k) \right),\end{aligned}$$

for some  $\gamma_{1,2} > 1$ , the parameters  $c_k, d_k$  are selected as

$$c_k = \gamma_1 L_1(y^k), \quad d_k = \gamma_2 L_2(x^{k+1}).$$

# Convergence condition of PALM - everything in one slide

**Theorem (Bolte14)** For  $\Phi(x, y) = f(x) + g(y) + H(x, y)$ , sequence produced by PALM converges to a stationary point of  $\Phi$  if :

## Assumption 1

- $f : \mathbb{R}^n \rightarrow (-\infty + \infty]$  and  $g : \mathbb{R}^m \rightarrow (-\infty + \infty]$  are proper and lower semicontinuous
- $H : \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}$  is a  $C^1$ /smooth function

## Assumption 2

- $\inf_{\mathbb{R}^n \times \mathbb{R}^m} \Phi > -\infty$ ,  $\inf_{\mathbb{R}^n} f > -\infty$ ,  $\inf_{\mathbb{R}^m} g > -\infty$
- Partial gradient  $\nabla_x H(x, y)$  is globally Lipschitz with  $L_1(y)$  :

$$\|\nabla_x H(x_1, y) - \nabla_x H(x_2, y)\| \leq L_1(y)\|x_1 - x_2\| \forall x_1, x_2 \in \mathbb{R}^n$$

- Partial gradient  $\nabla_y H(x, y)$  is globally Lipschitz with  $L_2(x)$  :

$$\|\nabla_y H(x, y_1) - \nabla_y H(x, y_2)\| \leq L_2(x)\|y_1 - y_2\| \forall y_1, y_2 \in \mathbb{R}^m$$

- Lipschitz modulus  $L_1(y^k), L_2(x^k)$  are bounded

$$L_1^{\min} \leq L_1(y^k) \leq L_1^{\max}, \quad L_2^{\min} \leq L_2(x^k) \leq L_2^{\max}, \forall k$$

- $\nabla H$  is Lipschitz on bounded subsets of  $\mathbb{R}^n \times \mathbb{R}^m$

$$\left\| \left( \nabla_x H(x_1, y_1) - \nabla_x H(x_2, y_2), \nabla_y H(x_1, y_1) - \nabla_y H(x_2, y_2) \right) \right\| \leq M \|(x_1 - x_2, y_1 - y_2)\|$$

**Assumption 3**  $\Phi$  satisfies Kurdyka-Łojasiewicz property

# Convergence condition of PALM - the focus of part 1

**Theorem (Bolte14)** For  $\Phi(x, y) = f(x) + g(y) + H(x, y)$ , sequence produced by PALM converges to a stationary point of  $\Phi$  if :

## Assumption 1

- $f : \mathbb{R}^n \rightarrow (-\infty + \infty]$  and  $g : \mathbb{R}^m \rightarrow (-\infty + \infty]$  are proper and lower semicontinuous
- $H : \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}$  is a  $C^1$ /smooth function

## Assumption 2

- $\inf_{\mathbb{R}^n \times \mathbb{R}^m} \Phi > -\infty$ ,  $\inf_{\mathbb{R}^n} f > -\infty$ ,  $\inf_{\mathbb{R}^m} g > -\infty$
- Partial gradient  $\nabla_x H(x, y)$  is globally Lipschitz with  $L_1(y)$  :

$$\|\nabla_x H(x_1, y) - \nabla_x H(x_2, y)\| \leq L_1(y) \|x_1 - x_2\| \forall x_1, x_2 \in \mathbb{R}^n$$

- Partial gradient  $\nabla_y H(x, y)$  is globally Lipschitz with  $L_2(x)$  :

$$\|\nabla_y H(x, y_1) - \nabla_y H(x, y_2)\| \leq L_2(x) \|y_1 - y_2\| \forall y_1, y_2 \in \mathbb{R}^m$$

- Lipschitz modulus  $L_1(y^k), L_2(x^k)$  are bounded

$$L_1^{\min} \leq L_1(y^k) \leq L_1^{\max}, \quad L_2^{\min} \leq L_2(x^k) \leq L_2^{\max}, \forall k$$

- $\nabla H$  is Lipschitz on bounded subsets of  $\mathbb{R}^n \times \mathbb{R}^m$

$$\left\| \left( \nabla_x H(x_1, y_1) - \nabla_x H(x_2, y_2), \nabla_y H(x_1, y_1) - \nabla_y H(x_2, y_2) \right) \right\| \leq M \|(x_1 - x_2, y_1 - y_2)\|$$

**Assumption 3**  $\Phi$  satisfies Kurdyka-Łojasiewicz property

# Convergence condition of PALM – in other words

For  $\Phi(x, y) = f(x) + g(y) + H(x, y)$ , sequence generated by PALM converges if

- $f, g$  are proper, lower semicontinuous, lower bounded, extended value
- $H$  is smooth such that
  - ▶ All partial gradients are globally Lipschitz with  $L_{1,2}$
  - ▶ All Lipschitz constants  $L_1(y^k), L_2(x^k)$  are bounded

**Theorem (Bolte14)** Let  $\{z^k\}_{k \in \mathbb{N}} = \{x^k, y^k\}_{k \in \mathbb{N}}$  be the sequence generated by PALM which is assumed to be bounded, if the above are true, then

(1) The sequence of function value  $\{\Phi(z^k)\}_{k \in \mathbb{N}}$  is non-increasing. More precisely

$$\Phi(z^k) - \Phi(z^{k+1}) \geq \frac{\rho_1}{2} \|z^{k+1} - z^k\|^2, \quad \forall k \in \mathbb{N},$$

where  $\rho_1 = \min \{(\gamma_1 - 1)L_1^{\min}, (\gamma_2 - 1)L_2^{\min}\}$

(2) The trajectory of the sequence  $\{z^k\}_{k \in \mathbb{N}}$  has finite length

$$\sum_{k=1}^{\infty} \|z^{k+1} - z^k\| < \infty,$$

which implies the gap between consecutive iterates decrease with  $k$  and

$$\lim_{k \rightarrow \infty} \|z^{k+1} - z^k\| = 0.$$

# Material for the proof

1. From assumption 2 we have

- Partial gradient  $\nabla_x H(x, y)$  is globally Lipschitz with  $L_1(y)$  :

$$\|\nabla_x H(x_1, y) - \nabla_x H(x_2, y)\| \leq L_1(y) \|x_1 - x_2\| \forall x_1, x_2 \in \mathbb{R}^n$$

- Partial gradient  $\nabla_y H(x, y)$  is globally Lipschitz with  $L_2(x)$  :

$$\|\nabla_y H(x, y_1) - \nabla_y H(x, y_2)\| \leq L_2(x) \|y_1 - y_2\| \forall y_1, y_2 \in \mathbb{R}^n$$

2. Sufficient decrease lemma of proximal-gradient operator : for all  $u$ , on  $f(x) + g(x)$ , where  $f$  is  $L_f$  smooth but not convex and  $g$  is convex but non-smooth function, we have

$$f(u) + g(u) \geq f(u^+) + g(u^+) + \left(t - \frac{L_f}{2}\right) \|u^+ - u\|^2,$$

where  $u^+ = \text{prox}_t^g(u - t\nabla f(u))$  with  $t > L_f$ .

Details of sufficient decrease lemma : [see this slide](#). (The slide gives the sufficient decrease lemma for convex  $g$ , however the lemma also holds even if  $g$  is not convex, which is the case here)



## Material for the proof

Sufficient decrease lemma :

$$f(u) + g(u) \geq f(u^+) + g(u^+) + \left(t - \frac{L_f}{2}\right) \|u^+ - u\|^2,$$

Implies

$$f(u) + g(u) \geq f(u^+) + g(u^+) + \frac{t - L_f}{2} \|u^+ - u\|^2,$$

Re-arrange gives

$$f(u^+) + g(u^+) \leq f(u) + g(u) - \frac{t - L_f}{2} \|u^+ - u\|^2.$$

## Material for the proof

We have sufficient decrease lemma for proximal gradient operator :

$$f(u^+) + g(u^+) \leq f(u) + g(u) - \frac{t - L_f}{2} \|u^+ - u\|^2.$$

Recall problem : minimize  $\Phi(x, y) = f(x) + g(y) + H(x, y)$ , here  $H$  is smooth and  $f, g$  are not smooth and PALM on  $\Phi$  steps are

$$\begin{aligned}x_k &\in \text{prox}_{f, c_k} \left( x^k - \frac{1}{c_k} \nabla_x H(x^k, y^k) \right), \\y_k &\in \text{prox}_{g, d_k} \left( y^k - \frac{1}{d_k} \nabla_y H(x^{k+1}, y^k) \right),\end{aligned}$$

Therefore, we can see that, we should apply the sufficient decrease lemma on  $\Phi$  by putting the smooth function as  $H(x, y)$  and the non-smooth parts as  $f, g$

## The proof - 1. apply sufficient decrease lemma

Apply the sufficient decrease lemma for proximal gradient operator :

$$f(u^+) + g(u^+) \leq f(u) + g(u) - \frac{t - L_f}{2} \|u^+ - u\|^2.$$

On PALM twice :

First time on  $x$  : smooth part  $H(\cdot, y)$ , non-smooth part  $f(x)$ , step size  $t = c_k = \gamma_1 L_1(y)$  with  $\gamma_1 > 1$  so that  $t \geq L_{H(\cdot, y)} = L_1(y)$

$$H(x^{k+1}, y^k) + f(x^{k+1}) \leq H(x^k, y^k) + f(x^k) - \frac{c_k - L_1(y^k)}{2} \|x^{k+1} - x^k\|_2^2$$

Second time on  $y$  : smooth part  $H(x, \cdot)$ , non-smooth part  $g(x)$ , step size  $t = d_k = \gamma_2 L_2(x)$  with  $\gamma_2 > 1$  so that  $t \geq L_{H(x, \cdot)} = L_2(x)$

$$H(x^{k+1}, y^{k+1}) + g(y^{k+1}) \leq H(x^{k+1}, y^k) + g(x^k) - \frac{d_k - L_2(x^{k+1})}{2} \|y^{k+1} - y^k\|_2^2$$

## The proof - 1. apply sufficient decrease lemma

We now have

$$H(x^{k+1}, y^k) + f(x^{k+1}) \leq H(x^k, y^k) + f(x^k) - \frac{c_k - L_1(y^k)}{2} \|x^{k+1} - x^k\|_2^2$$

$$H(x^{k+1}, y^{k+1}) + g(y^{k+1}) \leq H(x^{k+1}, y^k) + g(x^k) - \frac{d_k - L_2(x^{k+1})}{2} \|y^{k+1} - y^k\|_2^2$$

Put  $c_k = \gamma_1 L_1(y^k)$  and  $d_k = \gamma_2 L_2(x^{k+1})$  gives

$$H(x^{k+1}, y^k) + f(x^{k+1}) \leq H(x^k, y^k) + f(x^k) - \frac{\gamma_1 - 1}{2} L_1(y^k) \|x^{k+1} - x^k\|_2^2$$

$$H(x^{k+1}, y^{k+1}) + g(y^{k+1}) \leq H(x^{k+1}, y^k) + g(x^k) - \frac{\gamma_2 - 1}{2} L_2(x^{k+1}) \|y^{k+1} - y^k\|_2^2$$

Next step : sum the two equations

## The proof - 2. sum the two equations

Sum the two equations gives

$$\begin{aligned} & H(x^{k+1}, y^k) + f(x^{k+1}) + H(x^{k+1}, y^{k+1}) + g(y^{k+1}) \\ \leq & H(x^k, y^k) + f(x^k) - \frac{\gamma_1 - 1}{2} L_1(y^k) \|x^{k+1} - x^k\|_2^2 \\ & + H(x^{k+1}, y^k) + g(x^k) - \frac{\gamma_2 - 1}{2} L_2(x^{k+1}) \|y^{k+1} - y^k\|_2^2 \end{aligned}$$

Recall :  $\Phi(x, y) = f(x) + g(y) + H(x, y)$ , so

$$\begin{aligned} & H(x^{k+1}, y^k) + f(x^{k+1}) + H(x^{k+1}, y^{k+1}) + g(y^{k+1}) \\ \leq & H(x^k, y^k) + f(x^k) - \frac{\gamma_1 - 1}{2} L_1(y^k) \|x^{k+1} - x^k\|_2^2 \\ & + H(x^{k+1}, y^k) + g(x^k) - \frac{\gamma_2 - 1}{2} L_2(x^{k+1}) \|y^{k+1} - y^k\|_2^2 \end{aligned}$$

Becomes

$$\begin{aligned} & \Phi(x^{k+1}, y^{k+1}) \\ \leq & \Phi(x^k, y^k) - \frac{\gamma_1 - 1}{2} L_1(y^k) \|x^{k+1} - x^k\|_2^2 - \frac{\gamma_2 - 1}{2} L_2(x^{k+1}) \|y^{k+1} - y^k\|_2^2 \end{aligned}$$

Notice that the red parts cancel each other.

## The proof - 3. some simple algebra

Now we have

$$\begin{aligned} & \Phi(x^{k+1}, y^{k+1}) \\ \leq & \Phi(x^k, y^k) - \frac{\gamma_1 - 1}{2} L_1(y^k) \|x^{k+1} - x^k\|_2^2 - \frac{\gamma_2 - 1}{2} L_2(x^{k+1}) \|y^{k+1} - y^k\|_2^2 \end{aligned}$$

Rearrange gives

$$\begin{aligned} & \Phi(x^k, y^k) - \Phi(x^{k+1}, y^{k+1}) \\ \geq & \frac{\gamma_1 - 1}{2} L_1(y^k) \|x^{k+1} - x^k\|_2^2 + \frac{\gamma_2 - 1}{2} L_2(x^{k+1}) \|y^{k+1} - y^k\|_2^2 \end{aligned}$$

From assumption 2

$$L_1(y^k) \geq L_1^{\min}, \quad L_2(x^k) \geq L_2^{\min},$$

We have

$$\begin{aligned} & \Phi(x^k, y^k) - \Phi(x^{k+1}, y^{k+1}) \\ \geq & \frac{\gamma_1 - 1}{2} L_1^{\min} \|x^{k+1} - x^k\|_2^2 + \frac{\gamma_2 - 1}{2} L_2^{\min} \|y^{k+1} - y^k\|_2^2 \end{aligned}$$

## The proof - 3. some simple algebra

Now we have

$$\begin{aligned} & \Phi(x^k, y^k) - \Phi(x^{k+1}, y^{k+1}) \\ \geq & \frac{\gamma_1 - 1}{2} L_1^{\min} \|x^{k+1} - x^k\|_2^2 + \frac{\gamma_2 - 1}{2} L_2^{\min} \|y^{k+1} - y^k\|_2^2 \end{aligned}$$

Let  $\rho_1 = \min \{(\gamma_1 - 1)L_1^{\min}, (\gamma_2 - 1)L_2^{\min}\}$ , then

$$\begin{aligned} \Phi(x^k, y^k) - \Phi(x^{k+1}, y^{k+1}) & \geq \frac{\rho_1}{2} \|x^{k+1} - x^k\|_2^2 + \frac{\rho_1}{2} \|y^{k+1} - y^k\|_2^2 \\ & = \frac{\rho_1}{2} \left( \|x^{k+1} - x^k\|_2^2 + \|y^{k+1} - y^k\|_2^2 \right) \end{aligned}$$

Hence for  $z^k = \{x_k, y_k\}$ ,

$$\Phi(z^k) - \Phi(z^{k+1}) \geq \frac{\rho_1}{2} \|z^{k+1} - z^k\|_2^2.$$

The proof of (1) is completed. Next we prove (2).

# The proof of finite trajectory length (1/3)

Let  $N$  be a positive integer, consider the trajectory from iteration 0 to  $N$  :

$$\sum_{k=0}^{N-1} \|x^{k+1} - x^k\|_2^2 + \|y^{k+1} - y^k\|_2^2 = \sum_{k=0}^{N-1} \|z^{k+1} - z^k\|_2^2.$$

By (1) we have

$$\begin{aligned} \sum_{k=0}^{N-1} \|z^{k+1} - z^k\|_2^2 &\leq \sum_{k=0}^{N-1} \frac{2}{\rho_1} \left( \Phi(z^k) - \Phi(z^{k+1}) \right) \\ &= \frac{2}{\rho_1} \sum_{k=0}^{N-1} \Phi(z^k) - \Phi(z^{k+1}) \end{aligned}$$

The term  $\sum_{k=0}^{N-1} \Phi(z^k) - \Phi(z^{k+1})$  forms a telescoping series :

$$\sum_{k=0}^{N-1} \Phi(z^k) - \Phi(z^{k+1}) = \Phi(z^0) - \underbrace{\Phi(z^1) + \Phi(z^1) - \Phi(z^2) + \dots + \Phi(z^{N-1})}_{\text{cancel out}} - \Phi(z^N)$$



## The proof of finite trajectory length (2/3)

We have

$$\sum_{k=0}^{N-1} \|z^{k+1} - z^k\|_2^2 \leq \frac{2}{\rho_1} \left( \Phi(z^0) - \Phi(z^N) \right)$$

Take limit  $N \rightarrow \infty$

$$\sum_{k=0}^{\infty} \|z^{k+1} - z^k\|_2^2 \leq \frac{2}{\rho_1} \left( \Phi(z^0) - \Phi(z^\infty) \right)$$

As we assume  $\Phi$  is bounded below (assumption 2), i.e.  $\inf \Phi > -\infty$ , and by the fact  $\Phi(z^k) \geq \inf \Phi$  for all  $k$  (even if  $k \rightarrow \infty$ ), therefore we have

$$-\Phi(z^\infty) \leq -\inf \Phi < -(-\infty) = +\infty$$

Hence

$$\sum_{k=0}^{\infty} \|z^{k+1} - z^k\|_2^2 \leq \frac{2}{\rho_1} \left( \Phi(z^0) - \inf \Phi \right) < +\infty$$

The proof is completed.

For  $\Phi(x, y) = f(x) + g(y) + H(x, y)$ , if

- $f, g$  are proper, lower semicontinuous, lower bounded, extended value
- $H$  is smooth such that
  - ▶ All partial gradients are globally Lipschitz with  $L_{1,2}$
  - ▶ All Lipschitz constants  $L_1(y^k), L_2(x^k)$  are bounded

Then the bounded sequence  $\{x^k, y^k\}_{k \in \mathbb{N}}$  generated by PALM has the following properties

- The sequence  $\{\Phi(z^k)\}_{k \in \mathbb{N}}$  is non-increasing.
- The trajectory of  $\{x^k, y^k\}_{k \in \mathbb{N}}$  has finite length, and therefore  $\{x^k, y^k\}_{k \in \mathbb{N}}$  converges (to some unknown point).

What is not proved : the above only proves  $\{x^k, y^k\}_{k \in \mathbb{N}}$  converges to some unknown points, it does not say anything on  $\{x^k, y^k\}_{k \in \mathbb{N}}$  converges to a stationary point of  $\Phi$ . For convergence to a stationary point, see part 2.

End of document