

What's happening in Nonnegative Matrix Factorization

A high level overview in 3 parts

Andersen Ang

Mathématique et recherche opérationnelle, UMONS, Belgium

Supervisor : Nicolas Gillis

Homepage: angms.science

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Part I.
Introduction

Non-negative Matrix Factorization (NMF)

Given :

- A matrix $\mathbf{X} \in \mathbb{R}_{+}^{m \times n}$.
- A positive integer $r \in \mathbb{N}$.

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- Important : everything is **non-negative**.



Exact and approximate NMF

Given the pair $(\mathbf{X} \in \mathbb{R}_{+}^{m \times n}, r \in \mathbb{N})$, find the pair $(\mathbf{W} \in \mathbb{R}_{+}^{m \times r}, \mathbf{H} \in \mathbb{R}_{+}^{r \times n})$ such that

$$\mathbf{X} = \mathbf{W}\mathbf{H}.$$

This is called *exact NMF*, **NP-hard** (Vavasis, 2007).

Exact and approximate NMF

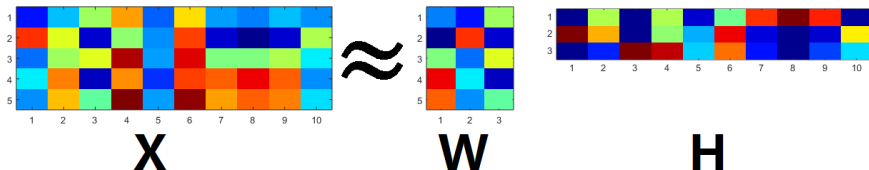
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(Low-rank) *approximate NMF* :

$$\mathbf{X} \approx \mathbf{W}\mathbf{H}, \quad 1 \leq r \leq \min\{m, n\}.$$



Find $(\mathbf{W}, \mathbf{H})$ numerically

Given $(\mathbf{X} \in \mathbb{R}_{+}^{m \times n}, r \leq \min\{m, n\})$, find
 $(\mathbf{W} \in \mathbb{R}_{+}^{m \times r}, \mathbf{H} \in \mathbb{R}_{+}^{r \times n})$ s.t. $\mathbf{X} \approx \mathbf{WH}$ via solving

$$[\mathbf{W}, \mathbf{H}] = \arg \min_{\mathbf{W} \geq \mathbf{0}, \mathbf{H} \geq \mathbf{0}} \|\mathbf{X} - \mathbf{WH}\|_F.$$

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- Minimizing the distance[†] between $\mathbf{X}$ and the approximator $\mathbf{WH}$ in **F-norm**.
- $\geq$ is element-wise (not positive semi-definite).
- Such **non-convex** minimization problem is **ill-posed and also NP-hard** (Vavasis, 2007).

* From now on, the inequality notations $\geq \mathbf{0}$ will be skipped.

[†]This talk does not consider other distance functions.

The scope of this talk

Given $(\mathbf{X}, r)$, find $(\mathbf{W}, \mathbf{H})$ via solving

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where $\star$: additional constraint(s)/regularization(s) that make the problem "better".

$\star$ in this talk :

- Nothing (this part) - NMF in the original form, being a NP-hard and ill-posed problem.
- Separability (part II) - to tackle the NP-hardness.
- Minimum volume (part III) - to generalize the separability.

Q : What about sparsity regularizer ?

A : Non-negativity *induces* sparsity (sparse NMF not covered in this talk).

For non-NMF people : why NMF ?

- **Interpretability**

NMF beats similar tools (PCA, SVD, ICA) due to the interpretability on non-negative data.

- **Model correctness**

NMF can find ground truth (under certain conditions).

- **Mathematical curiosity**

NMF is related to some serious problems in mathematics.

- ~~My boss tell me to do it.~~

Why NMF - Hyper-spectral image application (1/2)

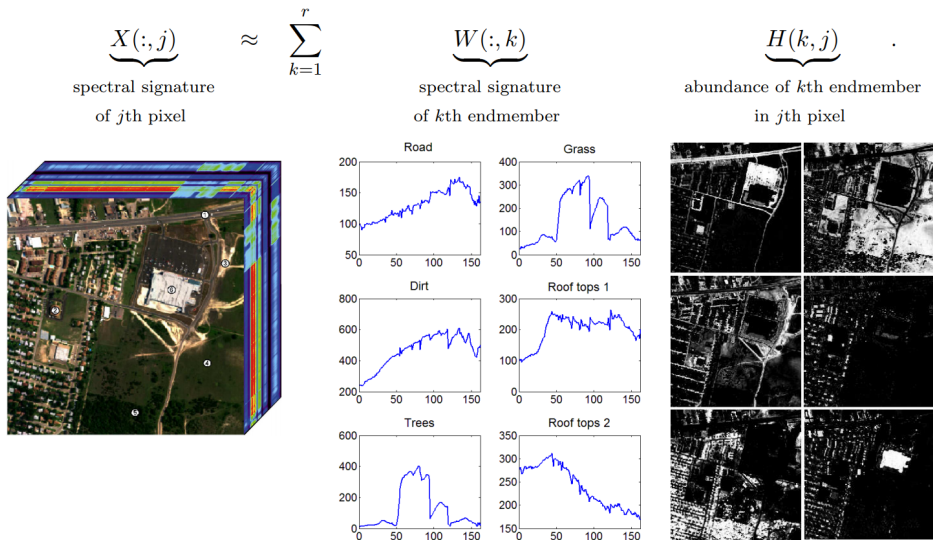


Figure: Hyper-spectral image decomposition. Figure shamelessly copied from (Gillis,2014).

Why NMF - Hyper-spectral image application (2/2)

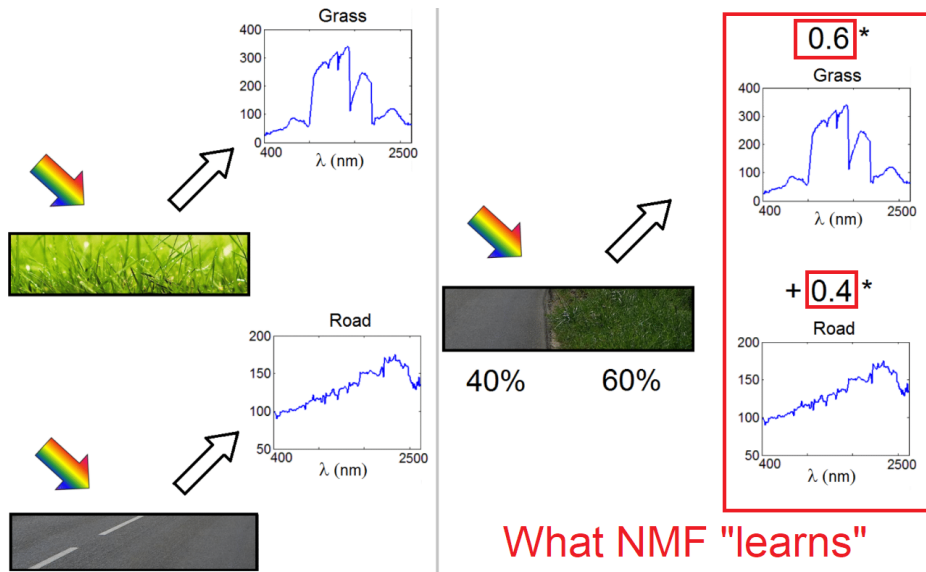


Figure: Hyper-spectral imaging. Figure modified from N. Gillis.

Why NMF - other examples

Application side

- Spectral unmixing in analytical chemistry (one of the earliest work)
- Representation learning on human face (the work that popularizes NMF)
- Topic modeling in text mining
- Probability distribution application on identification of Hidden Markov Model
- Bioinformatics : gene expression
- Time-frequency matrix decompositions for neuroinformatics
- (Non-negative) Blind source separation
- (Non-negative) Data compression
- Speech denoising
- Recommender system
- Face recognition
- Video summarization
- Forensics
- Art work conservation (identify true color used in painting)
- Medical imaging – image processing on small object
- Mid-infrared astronomy – image processing on large object
- 2 days ago : Tells whether a banana or a fish is healthy by "looking" at them

Theoretical numerical side

- A test-box for generic optimization programs : NMF is a constrained non-convex (but biconvex) problem
- Robustness analysis of algorithm
- Tensor
- Sparsity

Analytical side

- Non-negative rank $\text{rank}^+ :=$ smallest r such that

$$\mathbf{X} = \sum_{i=1}^r \mathbf{X}_i, \quad : \mathbf{X}_i \text{ rank-1 and non-negative.}$$

How to find / estimate / bound rank^+ , e.g. $\text{rank}_{\text{psd}}(\mathbf{X}) \leq \text{rank}^+(\mathbf{X})$.

- Extended formulations and combinatorics
- Log-rank Conjecture of communication system
- 3-SAT, Exponential time hypothesis, $\mathbf{P} \neq \mathbf{NP}$

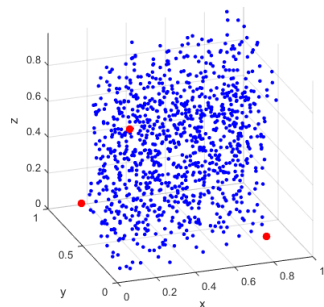
Part II.

NMF geometry & Separable NMF

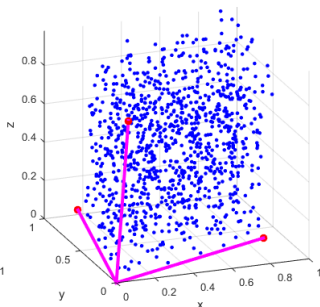
NMF tells a picture of a cone

Given $\mathbf{X}$, the NMF $\mathbf{X} = \mathbf{W}\mathbf{H}$ tells a picture of a
(non-negative simplicial[†] convex) cone.

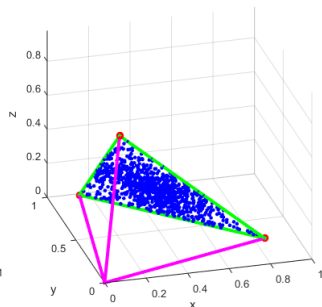
Data cloud



The cone



H normalized



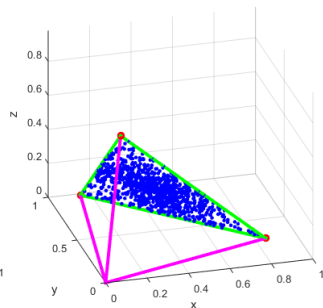
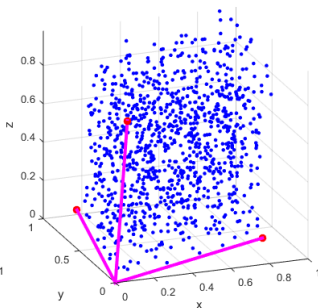
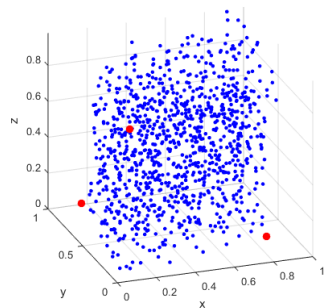
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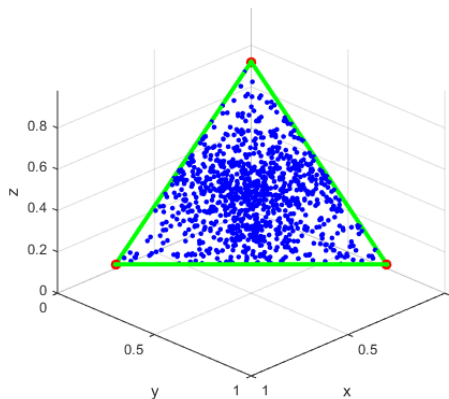
If the columns of $\mathbf{H}$ are normalized (sum-to-1), the cone becomes (compressed into) a convex hull.

[†]Assumes $\mathbf{W}$ is full rank.

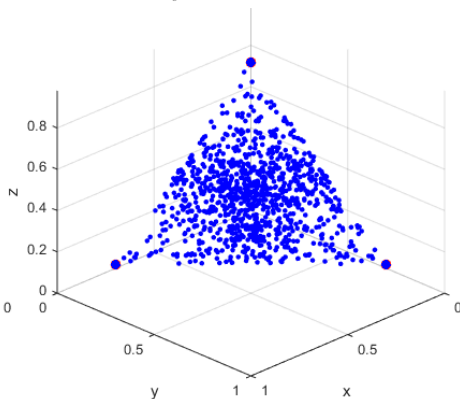
NMF tells a picture of a hull

For $r = 3$, facing the hull we see a **triangle**.

NMF



What you observed with data



$\text{NMF}_{(\mathbf{H} \text{ normalized})}$ problem geometrically means "find the **vertices**".

In this case, randomized NMF methods is a bad move : sub-sampling of data points remove the important points.

Separable Non-negative Matrix Factorization

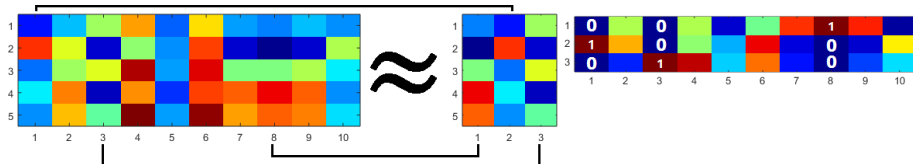
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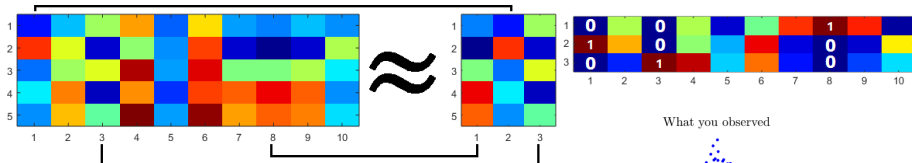
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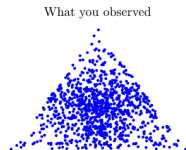
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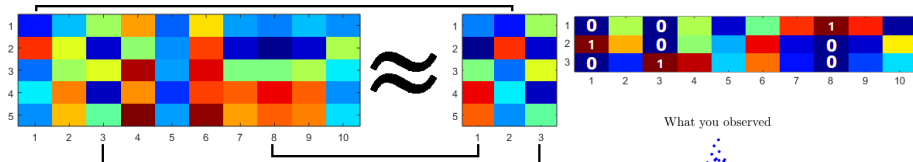
Geometry : $\mathbf{X}$ (data points) are convex combination (described by $\mathbf{H}$) of vertices ($\mathbf{W}$).



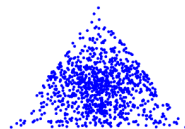
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Problem : find $\mathbf{W} \iff$ find **vertices** from **data cloud**.

- Not NP-hard anymore, solvable
- Algorithm : LP, SPA, X-ray, SNPA, ...

Separability (Donoho-Stodden, 2004)

"When Does Non-Negative Matrix Factorization Give a Correct Decomposition into Parts",
NIPS, 2014

Other names : pure pixel, anchor words, extreme ray, extreme point, generators.

Fast and robust algorithm for separable NMF

Problem : $[\mathbf{W}, \mathbf{H}] = \arg \min_{\mathbf{W}, \mathbf{H}} \|\mathbf{X} - \mathbf{WH}\|_F$ s.t. $\mathbf{W} = \mathbf{X}(:, \mathcal{J})$, $\mathbf{H} = [\mathbf{I}_r \mathbf{H}'] \mathbf{\Pi}_r$, $\mathbf{H}'^\top \mathbf{1} \leq \mathbf{1}$.

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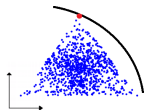
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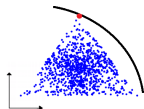
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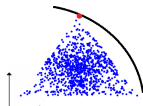
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- Step 3, 4, ... : repeat step 1-2, until $\mathbf{W}$ has r columns.
- How to get $\mathbf{H}$: with $(\mathbf{X}, \mathbf{W})$, do a non-negative least squares.



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In English : if noise is bounded, then the worse case fitting error is bounded.

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However, the success of SPA is based on the separability assumption :

"Vertices $\mathbf{W}$ are *presented* in observed data $\mathbf{X}$ "

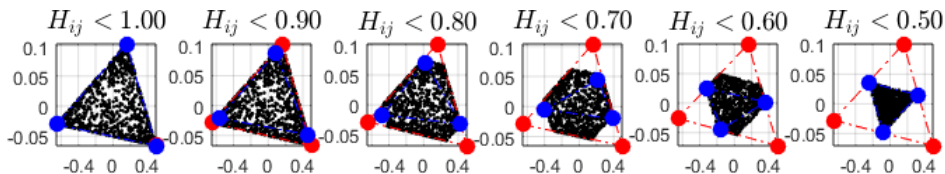
What if this is false ?

[†]Two examples : SNPA and preconditioned SPA by Gillis et al.

Part III.

Volume regularized NMFs

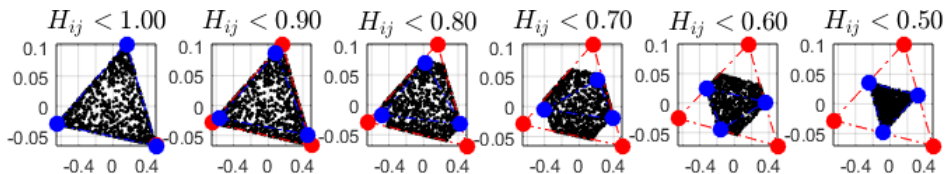
SPA fails when separability is false



Why fail : recall the first col. of $\mathbf{W}$ is extract as the col. of $\mathbf{X}$ with largest norm.

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How to solve it ??

Idea : minimum volume hull fitting : Click me.

(URL : <http://angms.science/eg underscore SNPA underscore ini dot gif>)

Volume regularized NMF

Idea : fitting with minimum volume.

Problem : $[\mathbf{W}, \mathbf{H}] = \arg \min_{\mathbf{W}, \mathbf{H}} \|\mathbf{X} - \mathbf{WH}\|_F + \lambda \mathcal{V}(\mathbf{W}),$

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Theoretical ground on recoverability : (Lin-Ma-Chi-Ambikapathi, 2015)

"Identifiability of the Simplex Volume Minimization Criterion for Blind Hyperspectral Unmixing: The No-Pure-Pixel Case", IEEE trans. Geosci. Remote Sensing, 2015.

† On which $\mathcal{V}$ is "computationally" better : (A.-Gillis, 2018)

"Volume regularized non-negative matrix factorizations",

IEEE WHISPERS18, Sep23-26, 2018, Amsterdam, NL.

Open problem : **fast** and **robust** algorithm for volume regularized NMF.

What are not discussed & open problems

- **How to actually solve NMF (and solve it fast)** - algorithm design
e.g. People now still keep using the **slow** multiplicative update
Gillis-Glineur, "Accelerated Multiplicative Updates and Hierarchical ALS Algorithms for Nonnegative Matrix Factorization", 2011.

A.-Gillis, "Accelerating Non-negative matrix factorization by extrapolation", to appear in *Neural Computation*, 2018.

- **Tuning of the regularization parameter λ**

For volume regularization, λ should be small and becoming smaller.

- **Other ideas**

- ▶ Non-negative tensor factorizations
- ▶ NMF + Sparsity (Cohen-Gillis, 2018, submitted)
- ▶ Non-negative rank $\text{rank}^+ :=$ smallest r such that

$$\mathbf{X} = \sum_{i=1}^r \mathbf{X}_i, \quad : \mathbf{X}_i \text{ rank-1 and non-negative.}$$

How to find / estimate / bound rank^+ , e.g. $\text{rank}_{\text{psd}}(\mathbf{X}) \leq \text{rank}^+(\mathbf{X})$.

- ▶ Combinatorial optimization, extended formulations.
- ▶ Log-rank Conjecture, Exponential time hypothesis, $\mathbf{P} \neq \mathbf{NP}$.

- Non-negative Matrix Factorization.
- Why NMF.
- Geometry of NMF.
- Separable NMF.
- When separability fails : minimum volume NMF.

Ideas are simple, devils in details.

END OF PRESENTATION.

slide in *angms.science*

ACK : my boss Nicolas Gillis, European Research Council Grant #679515.