

# Majorization Minimization - the Technique of Surrogate

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## 1 Introduction to Majorization Minimization

- What is Majorization Minimization
- Definition of surrogate

## 2 How to construct surrogate

- By quadratic upper bound of convex smooth function
- By quadratic lower bound of strongly convex function
- By Taylor expansion : 1st and 2nd order
- By inequalities

# What is Majorization Minimization

Majorization Minimization (MM) is an optimization algorithm.

More accurately, MM itself is not an algorithm, but a framework on how to construct an optimization algorithm.

Example of MM : Expectation Minimization (EM-Algorithm).

Another name of MM is "Successive upper bound minimization method".

# The idea of MM: Successive upper bound minimization

Want to solve  $\min_{x \in Q} f(x)$

How to solve : construct an iterative algorithm that produces a sequence  $\{x_k\}$  such that the objective function is non-increasing:  $f(x_{k+1}) \leq f(x_k)$

**Problem:** if  $f$  is **complicated**  $\implies$  cannot handle the problem *directly*

Idea: attack the problem *indirectly*

Generate the sequence  $\{x_k\}$  to minimize  $f$  by another **simpler** function  $g$  such that minimizing  $g$  'helps' minimizing  $f$ .

$g$  is called *surrogate function* / *auxiliary function*

How minimizing  $g$  'helps' minimizing  $f$  : if  $g$  is the upper bound of  $f$

# The idea of MM - Successive upper bound minimization

In other words, the idea of MM is:

1. [Original problem is too complicated]. Want to solve  $\min_{x \in Q} f(x)$ , but  $f$  is too complicated or solving  $\min_x f(x)$  directly is too expensive
- 2a. [Indirect attack of the problem via surrogate]. Finds/constructs a simpler function  $g$  that solving  $\min_{x \in Q} g(x)$  is cheaper
- 2b. Finally, use the solution of  $\min_x g(x)$  to solve  $\min_{x \in Q} f(x)$

Questions:

- how to find  $g$ ?
- how to use the information on  $g$  to minimize  $f$ ?

# The surrogate $g$

Surrogate function  $g(x)$  can be defined as a parametric function with the form

$$g(x|\theta)$$

where  $\theta$  is the parameter

In MM for minimization,  $\theta$  can be defined as  $x_k$ .

i.e. the information about the variable  $x$  at the current iteration is used to construct  $g$ .

The surrogate helps to minimize  $f$  by finding the variable in the next iteration as the minimizer of the current surrogate:

$$x_{k+1} = \arg \min_{x \in Q} g_k(x|x_k)$$

# Overall framework of MM

To solve

$$\min_{x \in \mathcal{Q}} f(x)$$

Use the following surrogate scheme:

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- (1) Initialize  $x_0$
  - (2) Construct a surrogate function at  $x_k$  as  $g_k(x|x_k)$
  - (3) Updating :  $x_{k+1} = \arg \min_{x \in \mathcal{Q}} g_k(x|x_k)$
  - (4) Repeat (2)-(3) until converge
- 

Note that the surrogate function is changing in each iteration, as  $g_k(x|x_k)$  depends on the changing variable  $x_k$

Also notice that the process of minimizing  $g$  will help minimizing  $f$  as the sequence  $\{x_k\}$  produced satisfies  $f(x_{k+1}) \leq f(x_k)$

# More questions

But, more exactly:

(1) how to construct  $g$ ?

(2) what is the condition of  $g$  ?

(3) how to optimize  $g$  ?

(4) how to know that optimizing  $g$  is cheaper than optimizing  $f$ ?



# Definition of surrogate

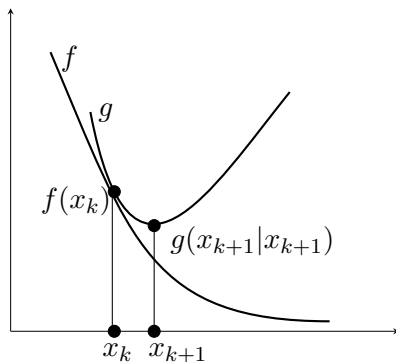
Two key conditions for surrogate  $g$  are:

1.  $g$  majorizes the original function  $f$  at  $x_k$  for all other points.

Mathematically,  $g_k(x|x_k) \geq f(x)$ ,  $\forall x, x^k \in \mathcal{Q}$ .

2.  $g$  touches the original function  $f$  at  $x_k$  at the point  $x = x_k$ .

Mathematically,  $g_k(x_k|x_k) = f(x_k)$ ,  $\forall x_k \in \mathcal{Q}$



# The convergence theorem of MM

**Theorem.** If the surrogate  $g$  satisfies the two conditions :

1.  $g(x|x_k) \geq f(x), \forall x.$
2.  $g(x_k|x_k) = f(x_k), \forall x_k.$

Then the iterative method  $x_{k+1} = \arg \min_{x \in \mathcal{Q}} g_k(x|x_k)$  will produce a sequence  $f(x_k)$  that converge to a local optimum. i.e.

$$f(x_{k+1}) \leq f(x_k)$$

Proof.

$$\begin{aligned} f(x_{k+1}) &\leq g(x_{k+1}|x_k) && \text{by condition 1} \\ &\leq g(x_k|x_k) && x_{k+1} \text{ minimizes } g \\ &= f(x_k) && \text{by condition 2} \end{aligned}$$



# Construct surrogate by quadratic upper bound of smooth convex function

Suppose  $f$  is convex (both  $f$  and  $\text{dom } f$ ) and  $\beta$ -smooth ( $\nabla f$  is Lipschitz continuous with parameter  $\beta$ ).

Then  $f$  is bounded above by the following at  $x_0 \in \text{dom } f$  for all  $x \in \text{dom } f$

$$f(x) \leq f(x_0) + \nabla f(x_0)^T (x - x_0) + \frac{\beta}{2} \|x - x_0\|_2^2$$

Surrogate can be defined as such upper bound.

$$g_k(x|x_k) \leq f(x_k) + \nabla f(x_k)^T (x - x_k) + \frac{\beta}{2} \|x - x_k\|_2^2$$

Pros: simple construction of  $f$

Cons: need the knowledge of  $\beta$

# Construct surrogate by quadratic lower bound of strongly convex function

Suppose we want to do Minorization Maximization (the opposite).

Suppose  $f$  is  $\alpha$ -strongly convex. Then  $f$  is bounded below by the following at  $x_0 \in \text{dom } f$  for all  $x \in \text{dom } f$

$$f(x) \geq f(x_0) + \nabla f(x_0)^T (x - x_0) + \frac{\alpha}{2} \|x - x_0\|_2^2$$

Surrogate can be defined as such upper bound.

$$g_k(x|x_k) \geq f(x_k) + \nabla f(x_k)^T (x - x_k) + \frac{\alpha}{2} \|x - x_k\|_2^2$$

Pros: simple construction of  $f$

Cons: need the knowledge of  $\alpha$

# Construct surrogate by first order Taylor expansion

**Taylor Expansion.** Taylor expansion of a differentiable  $f$  at a point  $x_0$  is

$$f(x) = f(x_0) + \nabla f^T(x_0)(x - x_0) + \mathcal{O}$$

where  $\mathcal{O}$  is higher order term.

If  $f$  is convex, the first order Taylor approximation is a global underestimator of  $f$ . i.e.  $f(x) \geq f(x_0) + \nabla f(x_0)^T(x - x_0)$ .

This is useful for Minorization Maximization.

If  $f$  is concave, the first order Taylor approximation is a global overestimator of  $f$ . i.e.  $f(x) \leq f(x_0) + \nabla f(x_0)^T(x - x_0)$ .

This is useful for Majorization Minimization.

# Construct surrogate by majorizing the second order Taylor expansion

Consider the Taylor expansion at  $x_0$  again

$$f(x) = f(x_0) + \nabla f^T(x_0)(x - x_0) + \mathcal{O}$$

Suppose  $f$  is twice differentiable. Now express explicitly the higher order term  $\mathcal{O}$  in Lagrangian form

$$\mathcal{O} = \frac{1}{2}(x - x_0)^T \nabla^2 f(\xi)(x - x_0)$$

where  $\xi$  is some constant (by mean value theorem).

Taylor expansion of  $f$  at point  $x_0$  becomes

$$f(x) = f(x_0) + \nabla f^T(x_0)(x - x_0) + \frac{1}{2}(x - x_0)^T \nabla^2 f(\xi)(x - x_0)$$

# Construct surrogate by majorizing the second order Taylor expansion

One can construct a surrogate in the following form

$$g(x|x_0) = f(x_0) + \nabla f^T(x_0)(x - x_0) + \frac{1}{2}(x - x_0)^T M(x - x_0)$$

if  $M \succeq \nabla^2 f(x), \forall x$

The key is  $M \succeq \nabla^2 f(x)$ , so if  $M - \nabla^2 f(x)$  is positive semi-definite  $\forall x$  (including the case  $x = \xi$ ), then

$$g(x|x_0) - f(x) = \frac{1}{2}(x - x_0)^T \left( M - \nabla^2 f(\xi) \right) (x - x_0) \geq 0$$

Hence  $g$  majorizes  $f$ .

How to form  $M$ :  $M = \nabla^2 f + \delta I$

# Construct surrogate by majorizing the second order Taylor expansion - Least Square Example

Consider  $f(x) = \|Ax - b\|^2$  (F-norm or 2-norm)

$$\begin{aligned}\|Ax - b\|^2 &= (Ax - b)^T(Ax - b) \\ &= x^T A^T Ax - x^T A^T b - b^T Ax + b^T b \\ &= x^T A^T Ax - 2x^T A^T b + b^T b\end{aligned}$$

$$\begin{aligned}\nabla_x \|Ax - b\|^2 &= 2A^T Ax - 2A^T b \\ &= 2A^T(Ax - b)\end{aligned}$$

$$\nabla_x^2 \|Ax - b\|^2 = 2A^T A$$

2nd order Taylor expansion of  $f(x) = \|Ax - b\|^2$  is

$$f(x) = f(x_0) + 2A^T(Ax_0 - b)(x - x_0) + 2(x - x_0)^T A^T A(x - x_0)$$

Thus the following  $g$  majorizes  $f$

$$g(x|x_0) = f(x_0) + 2A^T(Ax_0 - b)(x - x_0) + 2(x - x_0)^T M(x - x_0)$$

where  $M \succeq A^T A$  is a diagonal matrix. A simple way to construct  $M$  is  $M = A^T A + \delta I$  with  $\delta > 0$



# Construct surrogate by majorizing the second order Taylor expansion - NMF Example

In Non-negative Matrix Factorization, we have

$$f(W, h) = \|Wh - x\|_2^2$$

where  $x$  is given and  $W, h$  are variable.

2nd order Taylor expansion of  $f(W, h)$  is

$$f(W, h) = f(h_0) + 2W^T (Wh_0 - x) (h - h_0) + 2(h - h_0)^T W^T W (h - h_0)$$

We can construct  $M$  as  $M = \text{Diag}\left(\frac{[W^T W h]_i}{[h]_i}\right)$ , then  $M \succeq W^T W$  and

$$g(W, h) = f(h_0) + 2W^T (Wh_0 - x) (h - h_0) + 2(h - h_0)^T M (h - h_0)$$

For detail: see the slides "Convergence analysis of NMF algorithm", and the original paper by Lee and Seung 2001

# Construct surrogate by inequalities

**Jensen's inequality.** If  $f$  is convex, then

$$f\left(\sum_i \lambda_i t_i\right) \leq \sum_i \lambda_i f(t_i)$$

where  $\lambda_i \geq 0$  and  $\sum_i \lambda_i = 1$ .

Example. Let  $t_i = \frac{c_i}{\lambda_i}(x_i - y_i) + c^T y$ , then

$$\begin{aligned}\lambda^T t &= \sum_i \lambda_i t_i \\ &= \sum_i (c_i x_i - c_i y_i + \lambda_i c^T y) \\ &= \sum_i c_i x_i - \sum_i c_i y_i + \left(\sum_i \lambda_i\right) c^T y \\ &= c^T x - c^T y + c^T y \\ &= c^T x\end{aligned}$$

## Construct surrogate by inequalities

By Jensen's inequality  $f\left(\sum_i \lambda_i t_i\right) \leq \sum_i \lambda_i f(t_i)$

$$\begin{aligned} f\left(\lambda^T t\right) &\leq \sum_i \lambda_i f(t_i) \\ &= \sum_i \lambda_i f\left(\frac{c_i}{\lambda_i}(x_i - y_i) + c^T y\right) \end{aligned}$$

As  $\lambda^T t = c^T x$  thus

$$f(c^T x) \leq \sum_i \lambda_i f\left(\frac{c_i}{\lambda_i}(x_i - y_i) + c^T y\right)$$

So for a convex function  $f$ , the surrogate function of  $f(c^T x)$  is  $g(x|y) = \sum_i \lambda_i f\left(\frac{c_i}{\lambda_i}(x_i - y_i) + c^T y\right)$ , with  $\sum_i \lambda_i = 1$

## Construct surrogate by inequalities

Example. If  $c$ ,  $x$  and  $y$  are all positive, let  $t_i = \frac{x_i}{y_i} c^T y$  and  $\lambda_i = \frac{c_i y_i}{c^T y}$  (hence again  $\lambda^T t = c^T x$ ) then by Jensen's inequality

$$\begin{aligned} f(\lambda^T t) &\leq \sum_i \lambda_i f(t_i) \\ &= \sum_i \frac{c_i y_i}{c^T y} f\left(\frac{x_i}{y_i} c^T y\right) \end{aligned}$$

Hence

$$f(c^T x) \leq \sum_i \frac{c_i y_i}{c^T y} f\left(\frac{x_i}{y_i} c^T y\right)$$

So for a convex function  $f$ , the surrogate function of  $f(c^T x)$ , with positive  $c$  and  $x$  is  $g(x|y) = \sum_i \lambda_i f\left(\frac{c_i}{\lambda_i}(x_i - y_i) + c^T y\right)$ , where  $\sum_i \lambda_i = 1$  and  $y$  has to be positive.

Advantage of the surrogate in the two examples :  $g$  are separable and thus parallelizable.

# Construct surrogate by inequalities

Other inequalities :

Cauchy-Schwartz Inequality

$$|u^T v| \leq \|u\| \|v\|$$

Arithmetic-Geometric Mean

$$\left( \prod_i^n x_i \right)^{\frac{1}{n}} \leq \frac{1}{n} \sum_i^n x_i$$

Chebyshev, Hölder, and so on...

- Introduction of Majorization Minimization
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  - (3) Updating :  $x_{k+1} = \arg \min_{x \in \mathcal{Q}} g_k(x|x_k)$
  - (4) Repeat (2)-(3) until converge
- The surrogate function
  1.  $g$  majorizes the original function  $f$  at  $x_k$  for all other points. Mathematically,  $g_k(x|x_k) \geq f(x)$  ,  $\forall x, x^k \in \mathcal{Q}$ .
  2.  $g$  touches the original function  $f$  at  $x_k$  at the point  $x = x_k$ .
- Construction of surrogate function via various methods

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