

Generating uniform unit random vectors in \mathbb{R}^n

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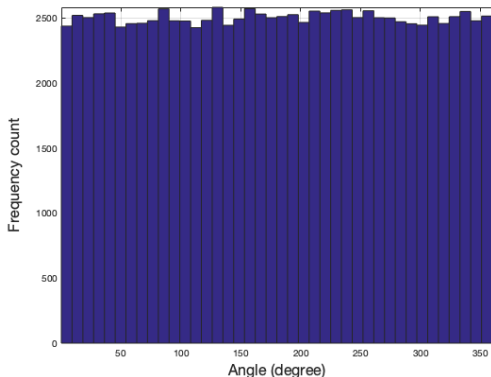
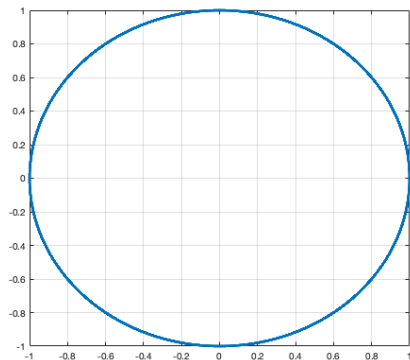
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Generating uniform distributed random unit vector in \mathbb{R}^2

Generating a random unit vector \mathbf{x} in \mathbb{R}^2 is the same as randomly picking a point on the circumference of a circle centred at the origin.

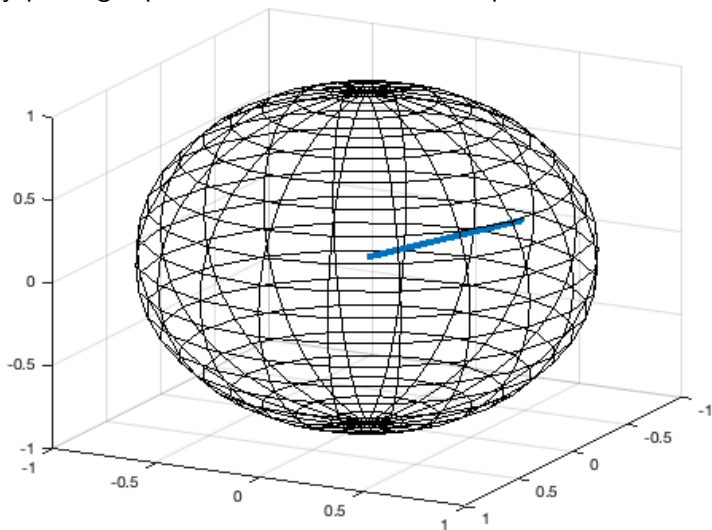
With the expression $\mathbf{x} = [\cos \theta \ \sin \theta]$, we can sample $\theta \sim \mathcal{U}[0, 2\pi]$, where \mathcal{U} stands for uniform distribution.



The points are uniformly distributed on the circumference.

Random unit vector in \mathbb{R}^3

In \mathbb{R}^3 , the same idea holds : generating a unit vector in \mathbb{R}^3 is the same as randomly picking a point on the surface of a 2-sphere¹.



¹A n -sphere is defined as $S^n = \{\mathbf{x} \in \mathbb{R}^{n+1} \mid \|\mathbf{x}\| = r\}$.

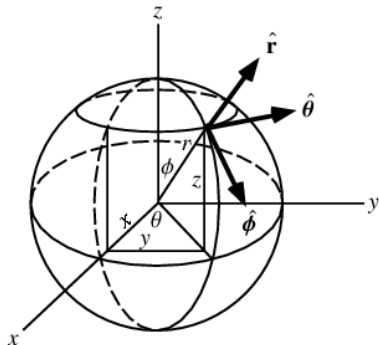
Expression of points on the surface of 2-sphere

The point on the surface of unit 2-sphere in \mathbb{R}^3 can be expressed as

$$\mathbf{x} = [\sin \phi \cos \theta \quad \sin \phi \sin \theta \quad \cos \phi],$$

where

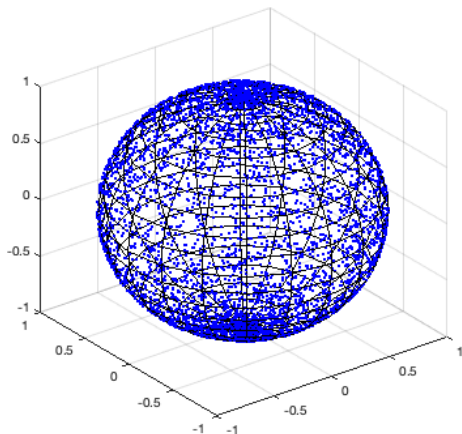
- θ is the azimuthal angle ranged in $[0 \ 2\pi]$
- ϕ is the polar angle ranged in $[0 \ \pi]$
- for unit 2-sphere the radius $r = 1$



Wrong way to generate uniform random unit vector in \mathbb{R}^3

As $\mathbf{x} = [\sin \phi \cos \theta \quad \sin \phi \sin \theta \quad \cos \phi]$, $\theta \in [0, 2\pi]$, $\phi \in [0, \pi]$. At first glance, to generate \mathbf{x} , one may pick $\phi \sim \mathcal{U}[0, \pi]$ and $\theta \sim \mathcal{U}[0, 2\pi]$.

This method does not work : the resulting points will not be uniform on the surface of the sphere, there will be more points at the two poles.

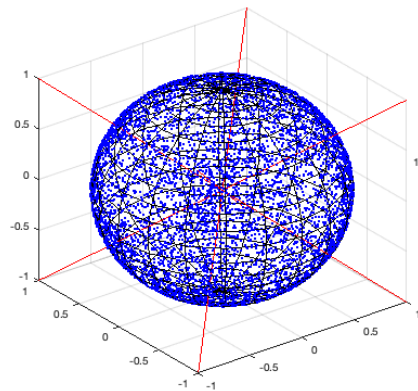


Wrong way to generate uniform random unit vector in \mathbb{R}^3

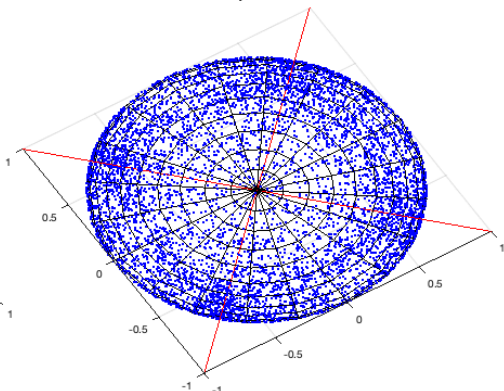
One may also generate \mathbf{x} by the *cube method* : randomly pick a point in $[-1, 1]^3$, then normalize it to have unit norm.

This method does not work : there will be more points on the diagonals.

3D view



Top view



Interesting fact : for $\mathbf{x} = [x \ y \ z]$, if \mathbf{x} is uniformly generated on the surface of the unit sphere, then (x, y, z) are all uniform in $[-1, 1]$, but the converse here is not true.

The modified cube method in \mathbb{R}^3 using rejection sampling

We can modify the cube method to generate \mathbf{x} :

- 1 Generate 3 random number $x, y, z \sim \mathcal{U}[-1, 1]$ (the cube method)
- 2 What's new : if $x^2 + y^2 + z^2 \leq 1$, let $\mathbf{x} = \frac{[x \ y \ z]}{\sqrt{x^2 + y^2 + z^2}}$.
Otherwise, reject the point and re-sample again.

The distribution of \mathbf{x} would be uniform on surface of the unit 2-sphere.

Why it works : only the points inside of unit ball are normalized, the points outside the sphere are rejected. This technique is called *Rejection sampling*.

Drawback of this approach : inefficient/slow, which is the fundamental disadvantage of all methods that use rejection sampling.

Why the modified cube method is inefficient

There are 2 step to generate \mathbf{x} :

- 1 Generate random number $x, y, z \sim \mathcal{U}[-1, 1]$
- 2 Rejection : if $x^2 + y^2 + z^2 > 1$, re-sample again

Rejecting sampled point means some computer resources are wasted to generate a useless point. That is, this method requires some random number generations before $x^2 + y^2 + z^2 \leq 1$ is true.

In fact, step 1 has to be run on average 2 to 3 time to generate a feasible point :

$$\mathbb{P}(x^2 + y^2 + z^2 \leq 1) = \frac{\text{Volume of the sphere}}{\text{Volume of the cube}} = \frac{4\pi r^3}{(2r)^3} = \frac{\pi}{6} \in \left[\frac{1}{3}, \frac{1}{2} \right].$$

The modified cube method is very inefficient in high dimension

The modified cube method works even worse when dimensions n is large. As the volume of unit ball shrinks fast in high dimension, it will require many random number generations before $x_1^2 + x_2^2 + \dots + x_n^2 \leq 1$ is true.

For example, when $n = 8$, we have volume of the unit 7-sphere as $4.06r^8$. Then

$$\mathbb{P}(x_1^2 + \dots + x_n^2 \leq 1) = \frac{4.06r^8}{(2r)^8} \approx \frac{1}{2^6} = \frac{1}{64}.$$

It takes roughly 64 random generations to form a feasible point.

If $n = 11$:

$$\mathbb{P}(x_1^2 + \dots + x_n^2 \leq 1) = \frac{1.884r^{11}}{(2r)^{11}} \approx \frac{1}{2^{10}} = \frac{1}{1024}.$$

It takes about 1000 generations to form a feasible point.

Efficient and simple way to pick random unit vector in \mathbb{R}^3

The following is an efficient and simple way to generate \mathbf{x} by using Gaussian random variable² : generate 3 independent Gaussian random variables $x, y, z \sim \mathcal{N}(0, 1)$. Then the distribution of

$$\mathbf{x} = \frac{[x \ y \ z]}{\sqrt{x^2 + y^2 + z^2}}$$

will be uniform over the surface of the sphere.

This works as multivariate normal distribution is *spherical*

- Further more, multivariate normal distribution is *symmetric* : it is invariant under rotation, so such approach is not the same as the cube method, points will not be concentrated on the diagonals
- Also, this method works for any dimension n

²M. E. Muller "A Note on a Method for Generating Points Uniformly on N-Dimensional Spheres." 1959.

Other ways to pick random unit vector in \mathbb{R}^3

There are other (more complicated) methods to generate \mathbf{x} in \mathbb{R}^3 :

Using equal-area projection of sphere onto rectangle surface of the bounding cylinder, we have

$$\mathbf{x} = \begin{bmatrix} \sqrt{1-z^2} \cos \theta & \sqrt{1-z^2} \sin \theta & z \end{bmatrix},$$

where $z \sim \mathcal{U}[-1, 1]$, $\theta \sim \mathcal{U}[0, 2\pi]$ and here $z = \cos \phi$ for the azimuthal angle ϕ .

On spherical coordinate, we can set

$$\theta \sim \mathcal{U}[0, 2\pi], \quad \phi = \cos^{-1} a,$$

where $a \sim \mathcal{U}[-1, 1]$. Then we set $\mathbf{x} = [\sin \phi \cos \theta \quad \sin \phi \sin \theta \quad \cos \phi]$.

Note that $\phi = \cos^{-1} a$, $a \sim \mathcal{U}[-1, 1]$ is different from directly picking $\phi \sim \mathcal{U}[0, \pi]$.

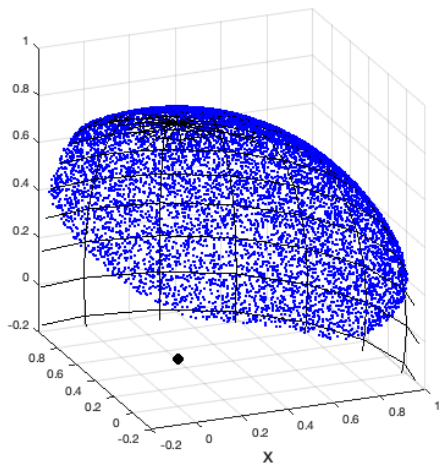
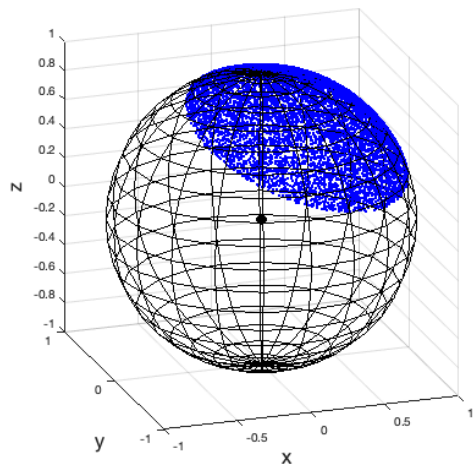
Generating uniform random unit vector in \mathbb{R}^n

To generate unit vector $\mathbf{x} = [x_1, x_2, \dots, x_n] \in \mathbb{R}^n$ such that \mathbf{x} is uniformly distributed on the surface of the unit $(n - 1)$ -sphere :

- 1 Generate n i.i.d. Gaussian random variable : $x_i \sim \mathcal{N}(0, 1)$.
- 2 Form $\mathbf{x} = [x_1, x_2, \dots, x_n]$.
- 3 Normalize \mathbf{x} to have unit l_2 norm.

Generating random unit vector in \mathbb{R}^3 within a cone

"Generating random unit vector in \mathbb{R}^n inside a cone" is the same as "picking a point on the partial surface of a $(n - 1)$ -sphere defined by the solid angle of the cone".



Points on the surface of 2-sphere inside a cone

The points on the surface of 2-sphere are

$$\mathbf{x} = [\sin \phi \cos \theta \quad \sin \phi \sin \theta \quad \cos \phi],$$

where

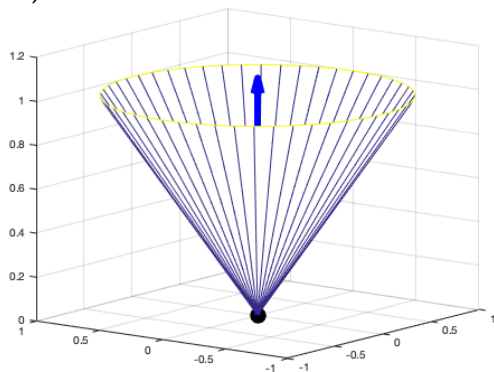
- θ is the azimuthal angle ranged in $[\theta_1, \theta_2] \subseteq [0, 2\pi]$
- ϕ is the polar angle ranged in $[\phi_1, \phi_2] \subseteq [0, \pi]$
- $\theta_1, \theta_2, \phi_1, \phi_2$ are all unknown value yet to be determined based on the information on the circular cone C

The characterization of circular cone $C(\mathbf{p}, \mathbf{d}, \psi)$

A circular cone C is completely determined by three parameters :

- the origin of the cone $\mathbf{p} \in \mathbb{R}^n$
- the direction of the cone $\mathbf{d} \in \mathbb{R}^n$
- the side angle of the cone $\psi \in [0, \pi]$

An example in \mathbb{R}^3 : $\mathbf{p} = [0, 0, 0]$ (the black dot), $\mathbf{d} = [0, 0, 1]$ (the blue arrow), $\psi = \frac{\pi}{4}$ (the angles between all the line on the yellow circle and \mathbf{d} are all equal to 45°)



Unit vector inside a cone

Now consider $n = 3$ and $\mathbf{p} = [0, 0, 0]$. (If the cone is not centred at origin, we can just translate it by adding \mathbf{p}). We are given a cone $C(\mathbf{d}, \psi)$, we want to generate unit vector such that these vectors are uniformly distributed inside the cone C .

How to generate these vectors:

$$\mathbf{x} = \left[\sqrt{1 - z^2} \cos \theta \quad \sqrt{1 - z^2} \sin \theta \quad z \right],$$

where $\theta \sim \mathcal{U}[0, 2\pi]$ and $z \sim \mathcal{U}[\cos \phi, 1]$, the polar angle ϕ is obtained by the z-component of the direction vector \mathbf{d} of the cone C , that is :

$$\phi = \cos^{-1} \langle [0, 0, 1], \hat{\mathbf{d}} \rangle = \cos^{-1} \left(\frac{\mathbf{d}_z}{\|\mathbf{d}\|_2} \right).$$

- Generating random unit vector in \mathbb{R}^n is the same as picking a point randomly on the surface of a unit $(n - 1)$ -sphere
- Wrong ways to generating random unit vector in \mathbb{R}^n
- Inefficient rejection sampling based method to generating random unit vector in \mathbb{R}^n
- Efficient way to generating random unit vector in \mathbb{R}^n
- A way to generating random unit vector within a cone in \mathbb{R}^3

Not discussed : how to generate random unit vector within a cone in \mathbb{R}^n

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