

Extrapolated Alternating Algorithms for Approximate Canonical Polyadic Decomposition

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Overview

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2. Existing Alternating Algorithms
3. Proposed Approaches
4. Experiments
5. Summary and Perspective

Paper information

- ▶ Paper number: WE3.L6.1
- ▶ Paper preprint:
<https://bit.ly/3aRn1yw>
- ▶ Slide available: angms.science

aCPD : Approximate Canonical Polyadic Decomposition

- ▶ Given a order p tensor $T \in \mathbb{R}^{n_1 \times n_2 \times \dots \times n_p}$ and a natural number r , find a tensor \hat{T} s.t.

$$\text{aCPD : } \hat{T} = \underset{\text{rank}(G) \leq r}{\text{argmin}} \left\| T - G \right\|_F^2,$$

- ▶ Rank of a tensor G defined as

$$\min \left\{ r \in \mathbb{N} \mid \exists a_i^{(j)} \in \mathbb{R}^{n_j}, G = \sum_{i=1}^r \bigotimes_{j=1}^p a_i^{(j)} \right\}.$$

- ▶ \otimes Tensor product

$$[a^{(1)} \otimes \dots \otimes a^{(p)}]_{i_1 \dots i_p} = \prod_{j=1}^p a_{i_j}^{(j)}.$$

- ▶ Motivation : A challenging task in general
 - ▶ Nonconvex problem.
 - ▶ Degeneracy and swamps.
 - ▶ Escaping saddle points.

Existing Alternating Algorithms

- ▶ Update one block at a time, while keeping others fixed
- ▶ Two categories

	Exact Block-Coordinate Descent	Approximate Block-Coordinate Descent
Subproblem	solved optimally	solved approximately
Example	Alternating Least Squares (ALS) Hierarchical ALS (HALS)	Various alternating gradient methods

- ▶ ALS update on block $A^{(j)}$

$$A_{\text{New}}^{(j)} = \underbrace{g(T, A^{(l \neq j)})}_{\text{update function}} := T_{[j]} B^{(j)\dagger}, \quad B^{jT} = \underbrace{\bigcirc_{l \neq j} A^{(l)}}_{\text{Khatri-Rao product}}.$$

- ▶ HALS : column-wise version of ALS.
- ▶ Gradient update on block $A^{(j)}$

$$A_{\text{New}}^{(j)} = A^{(j)} - \frac{1}{L^{(j)}} \left(A^{(j)} B^{jT} - T_{[j]} \right) B^j.$$

Proposed approaches

- ▶ Introduce 2 algorithms for computing aCPD that make use of extrapolation in 2 different ways

	Exact Block-Coordinate Descent	Approximate Block-Coordinate Descent
Proposed	Heuristic Extrapolation and Restart (HER)	Inertial Block Proximal Gradient (iBPG)
Convergence	Only empirical	With theoretical analysis

- ▶ Goal / contribution : show when computing aCPD, extrapolation can
 - ▶ enhance empirical convergence speed in difficult cases and
 - ▶ help escaping swamps.
- ▶ This observation is not new, can trace back to work by Harshman in 70s. We provide a fresh view on these issues by using more recent optimization techniques.

Algorithm 1 iBPG for CPD

1: Initialization: Set $\delta_w = 0.99$, $\beta = 1.01$, $t_0 = 1$,
2 sets of initial factor matrices $(A_{-1}^{(1)}, \dots, A_{-1}^{(p)})$ and
 $(A_0^{(1)}, \dots, A_0^{(p)})$. Set $k = 1$.

2: Set $A_{\text{prev}}^{(j)} = A_{-1}^{(j)}$, $j = 1, \dots, p$.

3: Set $A_{\text{cur}}^{(j)} = A_0^{(j)}$, $j = 1, \dots, p$.

4: **repeat**

5: **for** $j = 1, \dots, p$ **do**

6: $t_k = \frac{1}{2}(1 + \sqrt{1 + 4t_{k-1}^2})$, $\hat{w}_{k-1} = \frac{t_{k-1}-1}{t_k}$

7: $w_{k-1}^{(j)} = \min\left(\hat{w}_{k-1}, \delta_w \sqrt{\frac{L_{k-2}^{(j)}}{L_{k-1}^{(j)}}}\right)$

8: $L_k^{(j)} = \left\| (B_k^{(j)})^T B_k^{(j)} \right\|$

9: **repeat**

10: Compute two extrapolation points

$\hat{A}^{(j,1)} = A_{\text{cur}}^{(j)} + w_{k-1}^{(j)} (A_{\text{cur}}^{(j)} - A_{\text{prev}}^{(j)})$,

$\hat{A}^{(j,2)} = A_{\text{cur}}^{(j)} + \beta w_{k-1}^{(j)} (A_{\text{cur}}^{(j)} - A_{\text{prev}}^{(j)})$

11: Set $A_{\text{prev}}^{(j)} = A_{\text{cur}}^{(j)}$.

12: Update $A_{\text{cur}}^{(j)}$ by gradient step:

$$A_{\text{cur}}^{(j)} = \hat{A}^{(j,2)} - \frac{\left(\hat{A}^{(j,1)} (B_{k-1}^{(j)})^T - \mathcal{T}_{[j]}\right) B_{k-1}^{(j)}}{L_{k-1}^{(j)}}$$

13: **until** some criteria is satisfied

14: Set $A_k^{(j)} = A_{\text{cur}}^{(j)}$.

15: **end for**

16: Set $k = k + 1$.

17: **until** some criteria is satisfied

- ▶ An Alternating (proximal) grad. descent algo. to solve a general noncvx. nonsmooth block separable composite optimization problem.
 - ▶ Use 2 different extrapolation pts to compute gradient and to add inertial force.
 - ▶ No restarts.
 - ▶ Flexible in the choice of the order in which the blocks are updated.
 - ▶ Theory : iBPG for aCPD satisfies the condition for sub-sequential convergence. (Details in: arxiv:1903.01818)

Algorithm 2 herALS for CPD

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1: Initialization: Choose  $\beta_0 \in (0, 1)$ ,
    $\eta \geq \gamma \geq \bar{\gamma} \geq 1$ ,
   2 sets of initial factor matrices
    $(A_0^{(1)}, \dots, A_0^{(p)})$  and  $(Z_0^{(1)}, \dots, Z_0^{(p)})$ 
   Set  $\bar{\beta}_0 = 1$  and  $k = 1$ .

2: repeat
3:   for  $j = 1, \dots, p$  do
4:     Update:
        $A_k^{(j)} = g\left(T, \left[Z_k^{(l < j)}, Z_{k-1}^{(l > j)}\right]\right)$ 
5:     Extrapolate:
        $Z_k^{(j)} = A_k^{(j)} + \beta_k \left(A_k^{(j)} - A_{k-1}^{(j)}\right)$ 
6:   end for
7:   Compute  $\hat{F}_k = F(A_k^{(p)}; Z_k^{(l \neq p)})$ .
8:   if  $\hat{F}_k > \hat{F}_{k-1}$  for  $k \geq 2$  then
       Set  $Z_k^{(j)} = A_k^{(j)}$  for  $j = 1, \dots, p$ 
       Set  $\bar{\beta}_k = \beta_{k-1}$ ,
          $\beta_k = \beta_{k-1} / \eta$ 
9:   else
       Set  $A_k^{(j)} = Z_k^{(j)}$  for  $j = 1, \dots, p$ 
       Set  $\bar{\beta}_k = \max\{1, \bar{\beta}_{k-1} \bar{\gamma}\}$ ,
          $\beta_k = \max\{\bar{\beta}_{k-1}, \beta_{k-1} \gamma\}$ .
10:  end if should be "min"
11:  Set  $k = k + 1$ .
12: until some criteria is satisfied

```

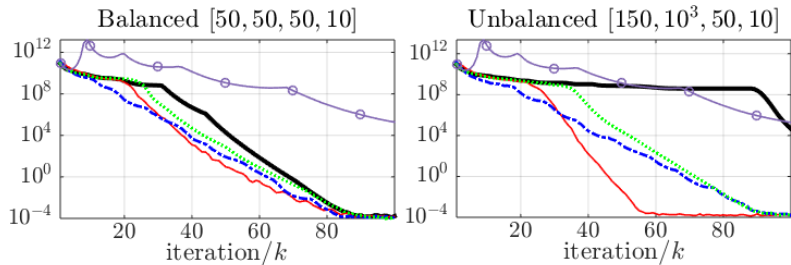
- ▶ An extrapolation of the factor estimates **between** each block update.
 - ▶ Parameters $(\eta, \gamma, \bar{\gamma})$.
 - ▶ Restarts based on criterion \hat{F} which is cheap to compute.
- ▶ Restart mechanism and β_k update
 - ▶ If \hat{F} decrease : we grow β .
 - ▶ If \hat{F} increase : we decrease β .
 - ▶ Similar update on $\bar{\beta}$.
- ▶ Not limited to ALS, HER can accelerate any BCD algo.
- ▶ No additional computational cost : cost of one iteration of herALS is the same as one iteration of ALS, because of the use of \hat{F} .
- ▶ No intensive parameter tuning is needed on $(\eta, \gamma, \bar{\gamma})$.
- ▶ On Nonnegative CPD: arXiv:2001.04321

Experiments setup

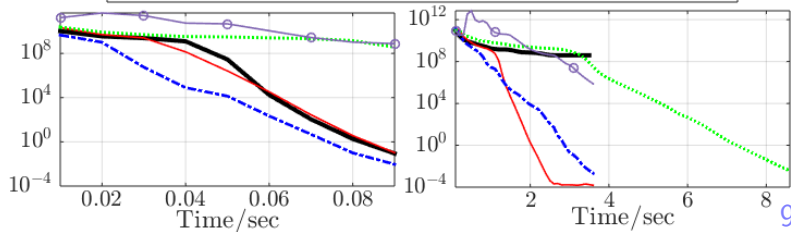
- ▶ Algorithms to compare : **iBPG** and **herALS**, and
 - ▶ **ALS** : Original un-accelerated ALS
 - ▶ **Bro-ALS** : accelerated ALS using Bro's acceleration, which uses a different heuristic approach to perform extrapolation.
 - ▶ **LS-ALS** : accelerated ALS where extrapolation sequence is computed by line search.
- ▶ Data sets : order 3 tensors, synthetic and real data from fluorescence spectroscopy and remote sensing.
- ▶ Data preprocessing : no preprocessing other than replacing NaN as 0.
- ▶ All experiments are run over 20 random initializations.
- ▶ Plotting : median of cost value over these 20 trials.

Synthetic data sets $T = \sum_{q=1}^r a_q^{(1)} \otimes a_q^{(2)} \otimes a_q^{(3)} + \sigma N$

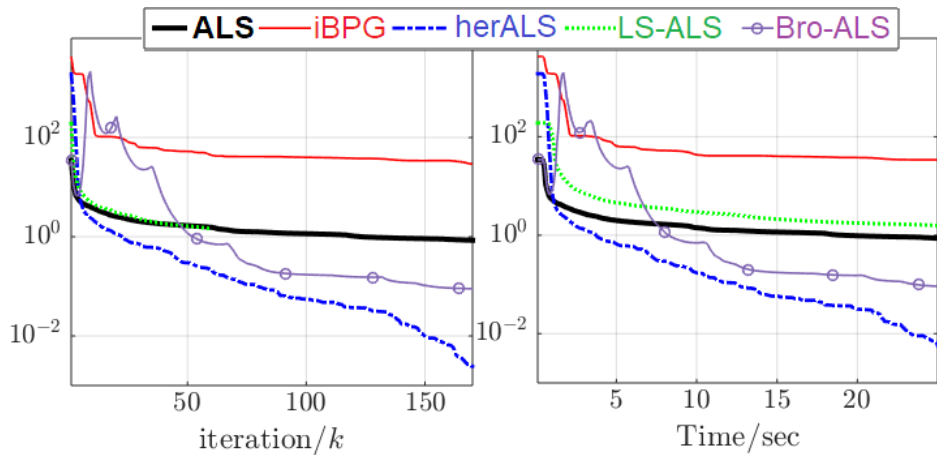
- ▶ N : zero mean unitary variance Gaussian noise
- ▶ Condition number of $A^{(j)}$ adjusted to 100 (ill-condition)
- ▶ Notation: $[I, J, K, r]$ is the tensor size and the factorization rank



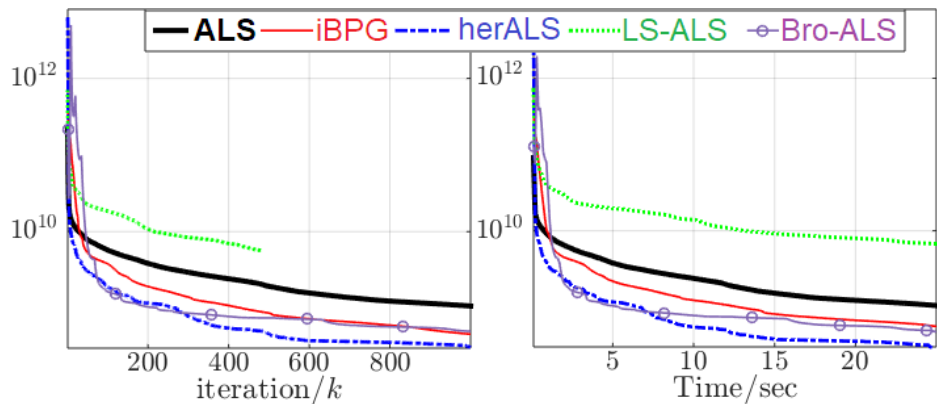
— ALS — iBPG - - - herALS LS-ALS ○ Bro-ALS

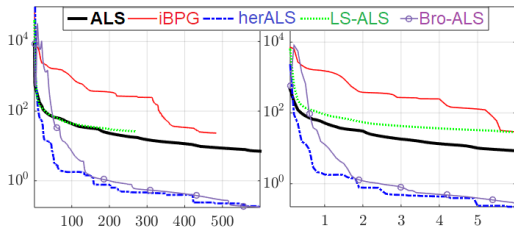


Wine data [44, 2700, 200, 15]



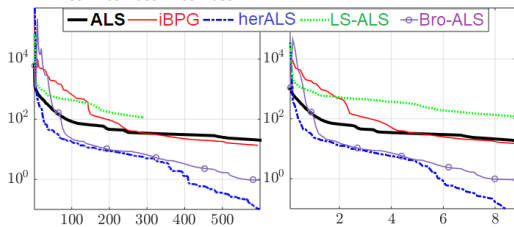
Indian Pines data [145, 145, 200, 16]



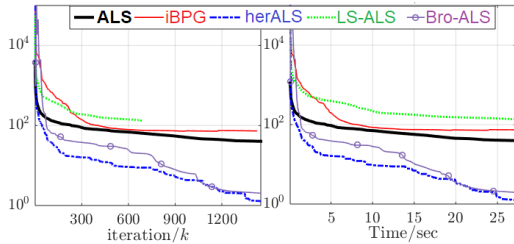


- ▶ Blood data $[289, 301, 41, r]$
 $r \in \{3, 6, 10\}$
 (top,middle,bottom)

On overall experiment results



- ▶ On synthetic data with ill-conditioned tensors, **iBPG** outperforms workhorse algo. **ALS**, and helps escaping swamps.



- ▶ On real data, **herALS** outperforms all tested methods while **iBPG** shows mitigated results.

Last page - summary and perspective

- ▶ Two extrapolation alternating algo. for solving aCPD : iBPG, HER-BCD.
- ▶ This work provides further practical evidence that extrapolation helps escaping swamps when computing aCPD.
- ▶ On constrained CPD, HER approach works even better for nonnegative CPD, see arXiv:2001.04321.
- ▶ Open problem : theoretical convergence analysis of HER.

Paper preprint: <https://bit.ly/3aRn1yw>

Slide: angms.science

End of presentation