

# Basics about digital image

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C0327 (2021-Spring)

2021-June -11

## What is an image

- A matrix of integers
- Each  $(i,j)$  element in the matrix is called a "pixel"
- The value of the pixel is the colour value (RGB) or brightness (BW)

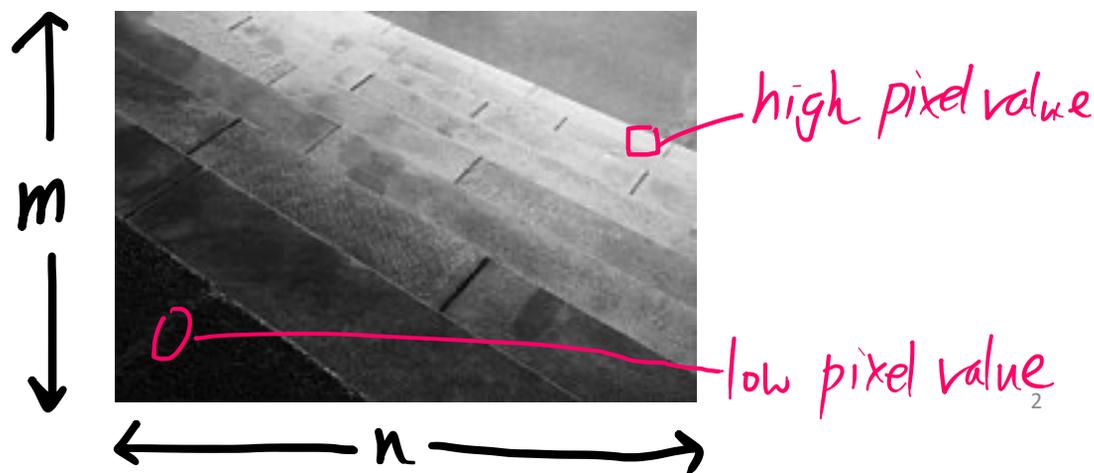
# Grayscale

- Integer in  $[0, 255]$
- 0 = total darkness
- 255 = total whiteness
- 0-255 has  $256 = 2^8$  integers



So, what is a grayscale image

- A matrix in  $\{0, 1, \dots, 255\}^{m \times n}$
- A bunch of integers



# Application of LP in image inpainting

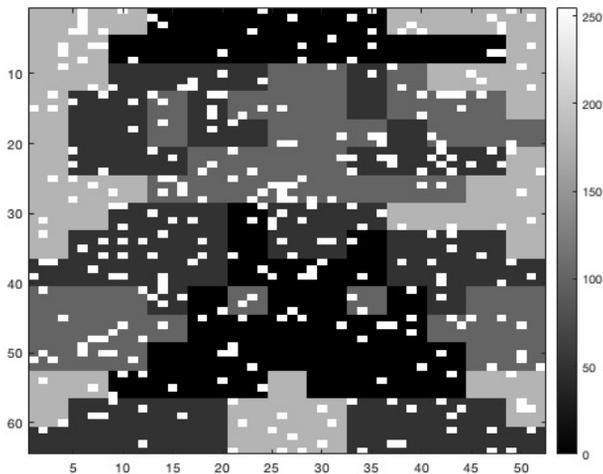
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2021-June-8

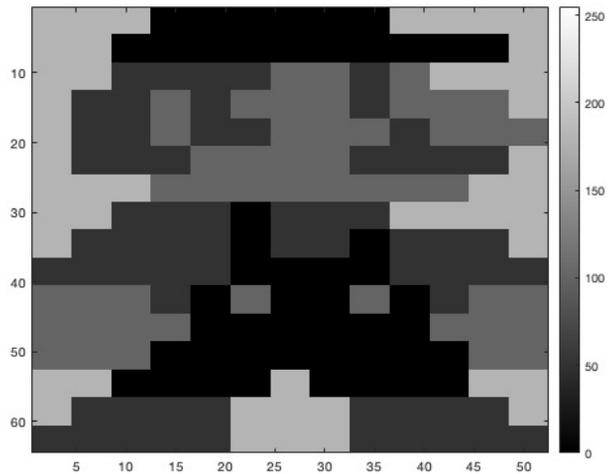
What is image inpainting

- Restore a "broken" image

Input



Output



The optimization problem of image recovery

$$\min \|Ex\|_1$$

$$\text{s.t. } Sx = \hat{x}_\Omega$$

$$x \geq 0$$

- $x$  is the optimization variable
- $E, S, \hat{x}_\Omega$  are given
- $x$  is the recovered image

## Vectorization

- Images are matrices, but we will work on vectors
- Matrix - to -vector transform is called vectorization

$$x = \text{vec}(X)$$

- In MATLAB, it is  $x = X(:);$

# Illustration of vectorization

1	4	7
2	5	8
3	6	9

$$X \in \mathbb{R}^{3 \times 3}$$

$\xrightarrow{\text{vec}}$

1
2
3
4
5
6
7
8
9

$$x \in \mathbb{R}^9$$

"stack columns"

$x$ ,  $\hat{x}_\Omega$  and  $x_0$

- $x_0$ : the original clean image vector
- $\hat{x}$ : the observed broken image vector
- $\hat{x}_\Omega$ : the parts of  $\hat{x}$  that are clean
- $\Omega$ : a set of indices of clean pixels
- $x$ : the recovered image vector

Example: 2-by-2 case

1	3
2	4

$X_0$

original image

1	*
*	4

$\hat{X}$

broken image

1
4

$\hat{X}_\Omega$

clean parts of  $\hat{X}$

?	?
?	?

$X$

recovered image (the variable)

1
2
3
4

$x_0$

Vectorized  $X_0$

1
*
*
4

$\hat{x}$

$\text{vec}(\hat{X})$

1
4

$\hat{x}_\Omega$

$\text{vec}(\hat{X}_\Omega)$

?
?
?
?

$x$

$\text{vec}(X)$

$$Sx = \hat{x}_\Omega$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$\Omega = \{1, 4\}$$

- $S$  is a matrix that map  $x$  to  $\hat{x}_\Omega$
- Meaning of  $Sx = \hat{x}_\Omega$ : "the recovered image has to match the clean pixels"
- 1st & 4th pixels in  $x$  has to match  $\hat{x}_\Omega$

# $\|Ex\|_1$

- It is called Total variation norm of  $x$
- TV = fluctuation
- Natural image has low fluctuation
- $E$  is a matrix of 1st-order difference

(Optional) What is total variation

$$\bullet TV(f) = \int_{\Omega} \|\nabla f(x)\|_p dx$$

"Sum"  $\nearrow$   
domain of focus  $\nearrow$  amount of variation measured by  $l_p$  norm

• TV of vector

$$TV(x) = \sum_{i=2}^n |x_{i+1} - x_i| = \left\| \begin{bmatrix} -1 & 1 & & \\ & -1 & 1 & \\ & & \ddots & \ddots \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \end{pmatrix} \right\|_1$$

$= |x_2 - x_1| + |x_3 - x_2| + \dots + |x_n - x_{n-1}|$

# The optimization problem of image recovery

$$\min_x TV(x)$$

$$\text{s.t. } Sx = \hat{x}_\Omega$$

$$x \geq 0$$

← recovered image has low TV

← recovered image fit the clean pixels

← pixels are nonnegative

- Not LP for the objective function

Turn  $TV(x)$  to a linear function

- $TV(x) = \|Ex\|_1$

- $E = \begin{bmatrix} I \otimes D \\ D \otimes I \end{bmatrix}$  is given

- $\ell_1$ -minimization

$$\min_x \|Ex\|_1$$

$$\text{s.t. } Sx = \hat{x}_\Omega$$

$$x \geq 0$$

} (\*)

Your task in assignment ~~4~~ 5

- Given  $E$ ,  $S$ ,  $\hat{x}_\Omega$  and  $\Omega$
- Write down a LP for recovery of the broken image
- Run MATLAB to solve the LP
- Show your image

What exactly you need to do

1. Turn (\*) in previous page to a LP
2. Write a code to solve this LP
3. Plot the recovered image

See ~~a4~~.pdf for more details.  
a5